User Manual
Anybus® Communicator™ for EtherCAT

Doc. Id. HMSI-168-95
Rev. 3.02

Connecting Devices™

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Important User Information

This document contains a general introduction as well as a description of the technical features provided by the Anybus Communicator, including the PC-based configuration software.

The reader of this document is expected to be familiar with PLC and software design, as well as communication systems in general. The reader is also expected to be familiar with the Microsoft Windows operating system.

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Warning:	This is a class A product. in a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.
ESD Note:	This product contains ESD (Electrostatic Discharge) sensitive parts that may be damaged if ESD control procedures are not followed. Static control precautions are required when handling the product. Failure to observe this may cause damage to the product.

Anybus Communicator for EtherCAT for Anybus Communicator
Rev 3.02
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Table of Contents

Preface **About This Document**

Related Documents ... 7
Document History ... 7
Conventions & Terminology ... 8
Glossary ... 8
Sales and Support ... 9

Chapter 1 **About the Anybus Communicator for EtherCAT**

External View ... 11
Status LEDs ... 12
Hardware Installation ... 13
Software Installation ... 14
Anybus Configuration Manager ... 14

Chapter 2 **Basic Operation**

General ... 15
Data Exchange Model ... 16
Memory Map ... 16
Data Exchange Example ... 17
Subnetwork Protocol ... 18
Protocol Modes ... 18
Protocol Building Blocks ... 18
Master Mode ... 19
Generic Data Mode ... 20
DF1 Master Mode ... 20
EtherCAT Communication Properties ... 21
General ... 21
Sync Managers ... 21
Data Representation ... 22

Chapter 3 **CANopen Object Dictionary Implementation**

Standard Objects ... 23
General ... 23
Object Entries ... 23
Manufacturer Specific Objects ... 24
Input Buffer ... 24
Output Buffer ... 25

Chapter 4 **Navigating the Anybus Configuration Manager**

Main Window ... 26
Pull-down Menu ... 27
Toolbar Icons ... 30

Chapter 5 Basic Settings

Fieldbus Settings ... 31
ABC Parameters ... 32
Subnetwork Parameters ... 34

Chapter 6 Nodes

General ... 35
Adding & Managing Nodes ... 35
Node Parameters ... 35
Master Mode and Generic Data Mode ... 35

Chapter 7 Transactions

General ... 36
Adding & Managing Transactions ... 37
Transaction Parameters (Master Mode) ... 38
Parameters (Query & Broadcast) ... 38
Parameters (Response) ... 40
Transaction Parameters (Generic Data Mode) ... 40
Produce-Transactions ... 40
Consume-Transactions ... 41
Transaction Editor ... 42

Chapter 8 Frame Objects

General ... 43
Adding and Editing Frame Objects ... 43
Constant Objects (Byte, Word, Dword) ... 44
Limit Objects (Byte, Word, Dword) ... 45
Data Object ... 46
Variable Data Object ... 46
Checksum Object ... 48

Chapter 9 Commands

General ... 49
Adding & Managing Commands ... 49
Pull-Down Menu ... 50
Toolbar Icons ... 50
The Command Editor ... 51
General ... 51
Basic Navigation ... 51
Pull-down Menu ... 52
Editing a Command ... 53
Example: Specifying a Modbus-RTU Command in Master Mode ... 54

Chapter 10 DF1 Protocol Mode

General ... 55
ABC Parameters ... 56
Subnetwork Parameters ... 57
Node Parameters ... 58
Services ... 58
Available Services ... 59
Integrity Check ... 60
Read Diagnostics ... 60
Read Data ... 61
Write Data ... 61

Chapter 11 Subnetwork Monitor

Chapter 12 Node Monitor

General ... 63
Navigating the Node Monitor ... 64
Pull-Down Menu ... 65
Toolbar Icons ... 66

Chapter 13 Data Logger

General ... 67
Operation ... 67
Configuration ... 68

Chapter 14 Configuration Wizards

General ... 69
Selecting a Wizard Profile ... 69
Wizard - Modbus RTU Master ... 70

Chapter 15 Control and Status Registers

General ... 71
Handshaking Procedure ... 71
Data Consistency ... 72
Status Register Contents (Gateway to Control System) ... 73
General Information ... 73
Status Codes in Master Mode and DF1 Master Mode ... 73
Status Code in Generic Data Mode ... 74
Control Register Contents (Control System to Gateway) ... 75
General Information ... 75
Control Codes in Master Mode and DF1 Master Mode ... 75
Control Codes in Generic Data Mode ... 75

Chapter 16 Advanced Fieldbus Configuration

General ... 76

Mailbox Editor 76

Appendix A Connector Pin Assignments

EtherCAT Connectors 77

Power Connector 77

PC Connector 78

Subnetwork Interface 79

General Information 79
Bias Resistors (RS485 Only) 79
Termination (RS485 & RS422 Only) 79
Connector Pinout (DB9F) 79
Typical Connection (RS485) 80
Typical Connection (RS422 & 4-Wire RS485) 80
Typical Connection (RS232) 80

Appendix B Technical Specification

Mechanical Properties 81

Electrical Characteristics 81

Environmental Characteristics 81

Regulatory Compliance 82

Appendix C Troubleshooting

Appendix D ASCII Table

About This Document

For more information, documentation etc., please visit the HMS website, www.anybus.com.

Related Documents

Document name	Author
ABC-ECT Installation Leaflet	HMS
DF1 Protocol and Command Set - Reference Manual, 1770-6.5.16, October 1996	Allen-Bradley

Document History

Summary of Recent Changes (3.01... 3.02)

Change	Page(s)
Added information on EtherCAT trademark	

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2.00	2007-05-07	PeP	All	1st official release
2.01	2007-08-13	PeP	-	Minor update
2.03	2009-04-24	KeL	All	Misc. minor corrections and updates
3.00	2011-02-09	KaD	All	Misc. minor updates, new template and DF1 functionality
3.01	2011-09-30	KaD	All	Misc corrections and updates, new Anybus Configuration Manager name
3.02	2012-11-20	KeL	I	Added information on EtherCAT trademark

Conventions & Terminology

The following conventions are used throughout this document:

- Numbered lists provide sequential steps
- Bulleted lists provide information, not procedural steps
- The term 'user' refers to the person or persons responsible for installing the Anybus Communicator in a network.
- The term 'gateway' refers to the Anybus Communicator.
- Hexadecimal values are written in the format 0xNNNN, where NNNN is the hexadecimal value.
- Decimal values are represented as NNNN where NNNN is the decimal value
- As in all communication systems, the terms "input" and "output" can be ambiguous, because their meaning depend on which end of the link is being referenced. The convention in this document is that "input" and "output" are always being referenced to the master/scanner end of the link.

Glossary

Term	Meaning
ABC	Anybus® Communicator™
Broadcaster	A protocol-specific node in the configuration that handles transactions destined to all nodes.
ECT	EtherCAT
Command	A predefined transaction.
Configuration	List of configured nodes with transactions on the subnetwork.
Fieldbus	The higher level network to which the communicator is connected.
Control System	Device which controls the communication on the higher level network, i.e. a fieldbus master
Frame Object	Low level entities which are used to describe the different parts of a transaction.
Monitor	A tool for debugging the gateway and the network connections.
Node	A device in the configuration which defines the communication with a node on the subnetwork
Subnetwork	The network that is logically located on a subsidiary level with respect to the fieldbus, and to which this product acts as a gateway.
Transaction	A generic building block that is used in the subnetwork configuration and defines the data that is sent and received on the subnetwork.
User	Person or persons responsible for installing the Anybus Communicator
Higher Level Network	In this case, EtherCAT
Network	
Fieldbus	

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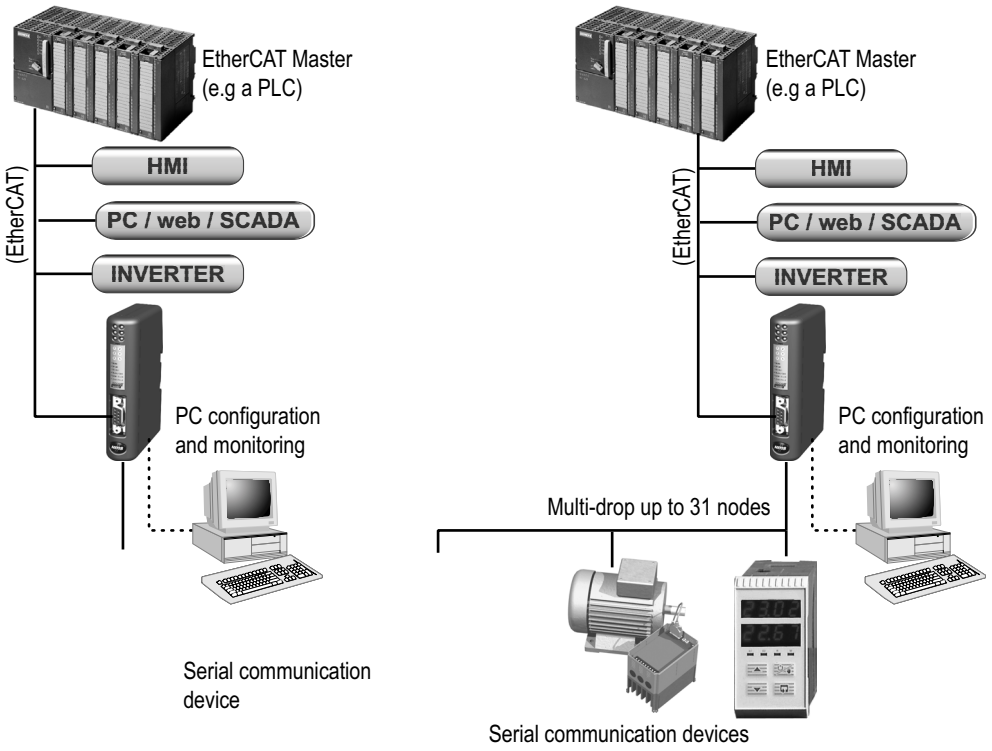
1. About the Anybus Communicator for EtherCAT

The Anybus Communicator for EtherCAT acts as a gateway between virtually any serial application protocol and an EtherCAT-based network. Integration of industrial devices is enabled without loss of functionality, control and reliability, both when retro-fitting to existing equipment as well as when setting up new installations.



Single-Node Serial Sub Network **Multi-Node Serial Sub Network**

Subnetwork

The gateway can address up to 31 nodes, and supports the following physical standards:

- RS-232
- RS-422
- RS-485

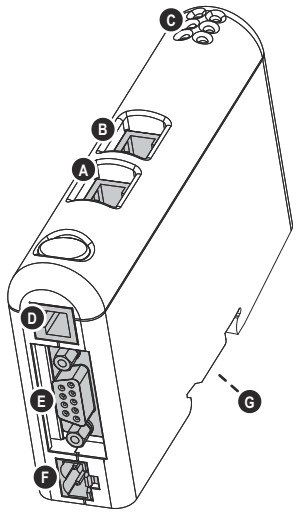
EtherCAT Interface

EtherCAT connectivity is provided through patented Anybus technology; a proven industrial communication solution used all over the world by leading manufacturers of industrial automation products.

- CANopen over EtherCAT
- DS301 v4.02 compliant
- Galvanically isolated network electronics
- Supports segmented SDO access
- Exchanges up to 512 bytes of data in each direction

1.1 External View

For wiring and pin assignments, see "Connector Pin Assignments" on page 77.



A: EtherCAT Port 1 (In)

See also...

- "EtherCAT Connectors" on page 77

B: EtherCAT Port 2 (Out)

See also...

- "EtherCAT Connectors" on page 77

C: Status LEDs

See also...

- "Status LEDs" on page 12

D: PC-connector

This connector is used to connect the gateway to a PC for configuration and monitoring purposes.

See also...

- "PC Connector" on page 78

E: Subnetwork Connector

This connector is used to connect the gateway to the serial subnetwork.

See also...

- "Subnetwork Interface" on page 79

F: Power Connector

This connector is used to apply power to the gateway.

See also...

- "Power Connector" on page 77
- "Troubleshooting" on page 83

G: DIN-rail Connector

The DIN-rail mechanism connects the gateway to PE (Protective Earth).

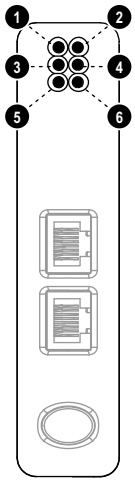
See also...

- "Hardware Installation" on page 13

1.2 Status LEDs

EtherCAT Interface Indications

#	State	Status
1 - RUN	Off	EtherCAT interface in INIT state
	Green	EtherCAT interface in OPERATIONAL state
	Green, blinking	EtherCAT interface in PREOPERATIONAL state
	Green, single flash	EtherCAT interface in SAFE-OPERATIONAL state
2 - ERR	Off	EtherCAT communication in working condition
	Red	Syncmanager watchdog timeout
	Red, blinking	General configuration error
	Red, single flash	Slave device application has changed the EtherCAT status autonomously: Parameter 'Change' in the AL status register is set to 01 (change/error)
	Red, double flash	Major internal fault.
3 - Link/Activity 1	Off	No link sensed on EtherCAT port 1
	Green	Link sensed on EtherCAT port 1
	Green, flickering	Activity on EtherCAT port 1
4 - Link/Activity 2	Off	No link sensed on EtherCAT port 2
	Green	Link sensed on EtherCAT port 2
	Green, flickering	Activity on EtherCAT port 2



General Gateway/Subnet Indications

#	State	Status
5 - Subnet Status[a]	Off	Power off
	Green, flashing	Running correctly, but one or more transaction error(s) have occurred
	Green	Running
	Red	Transaction error/timeout or subnet stopped
6 - Device Status	Off	Power off
	Alternating Red/Green	Invalid or missing configuration
	Green	Initializing
	Green, flashing	Running
	Red	Bootloader mode[b]
	Red, flashing	If the Device Status LED is flashing in a sequence starting with one or more red flashes, please note the sequence pattern and contact the HMS support department

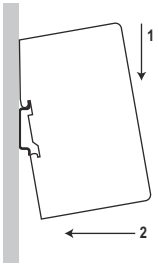
a. This led turns green when all transactions have been active at least once. This includes any transactions using "change of state" or "change of state on trigger". If a timeout occurs on a transaction, this led will turn red.

b. The gateway is in bootloader mode, and firmware must be restored in order for it to work properly. Start up the Anybus Configuration Manager and connect to the Anybus Communicator. Choose Tools/Options/ABC. Click "Factory Restore" to restore firmware. See "Tools" on page 28.

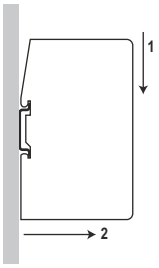
1.3 Hardware Installation

Perform the following steps when physically installing the gateway:

1. Snap the gateway on to the DIN-rail (See "DIN-rail Connector" on page 11)
   The DIN-rail mechanism works as follows:



To snap the gateway *on*, first press it downwards (1) to compress the spring in the DIN-rail mechanism, then push it against the DIN-rail as to make it snap on (2)



To snap the gateway *off*, push it downwards (1) and pull it out from the DIN-rail (2), as to make it snap off from the DIN-rail

2. Connect the gateway to the EtherCAT network
3. Connect the gateway to the serial subnetwork
4. Connect the gateway to the PC via the Configuration Cable
5. Connect the power cable and apply power
6. Start the Anybus Configuration Manager on the PC
   (The Anybus Configuration Manager software attempts to detect the serial port automatically. If not successful, select the correct port manually in the "Port"-menu)
7. Configure the gateway using the Anybus Configuration Manager and download the configuration

1.4 Software Installation

1.4.1 Anybus Configuration Manager

System requirements

- Pentium 133 MHz or higher
- 650 MB of free space on the hard drive
- 32 MB RAM
- Screen resolution of 800x600 (16 bit color) or higher
- Microsoft Windows™ 2000 / XP / Vista / 7 (32 bit)
- Internet Explorer 4.01 SP1 or newer

Installation

- **Anybus Communicator resource CD**

  Insert the CD and follow the on-screen instructions. If the installation does not start automatically, right-click on the CD-drive icon and select Explore. Execute 'setup.exe' and follow the on-screen instructions.

- **From website**

  Download and execute the self-extracting .exe-file from the HMS website (www.anybus.com).

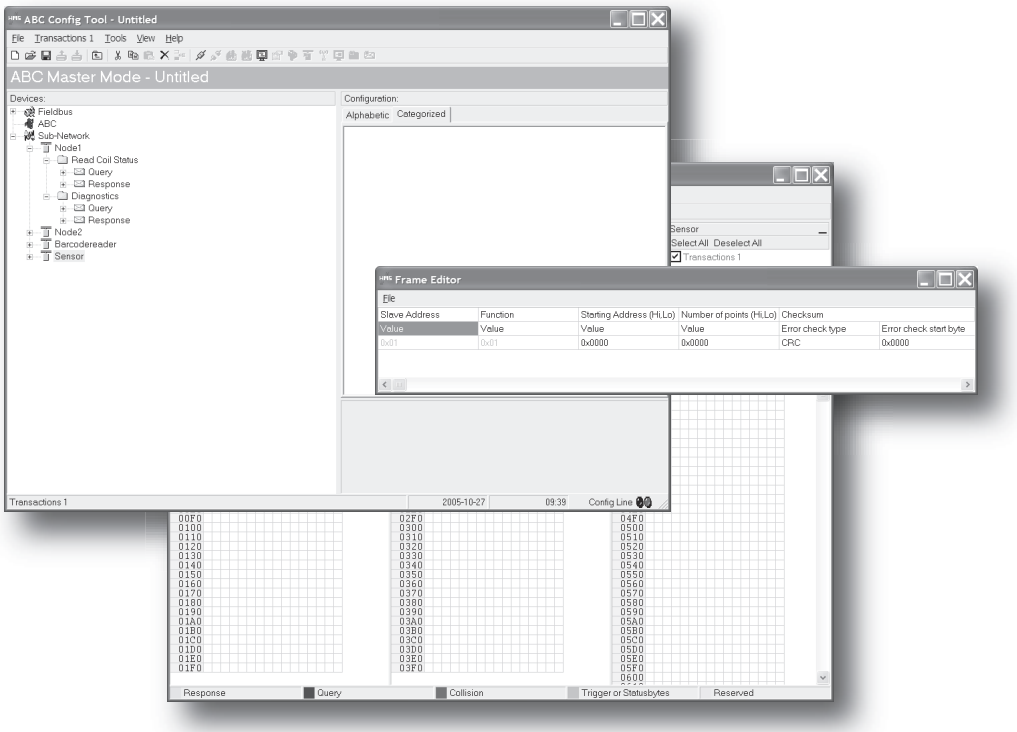
2. Basic Operation

2.1 General

The Anybus Communicator gateway is designed to exchange data between a serial subnetwork and a higher level network. Unlike most other gateway devices of similar kind, it does not have a fixed protocol for the subnetwork, and can be configured to handle almost any form of serial communication.

The gateway can issue serial telegrams cyclically, on change of state, or based on trigger events issued by the control system of the higher level network (i.e. the fieldbus master or PLC). It can also monitor certain aspects of the subnetwork communication and notify the higher level network when data has changed.

An essential part of the Anybus Communicator package is the Anybus Configuration Manager, a Windows™ application which is used to supply the gateway with a description of the subnetwork protocol. No programming skills are required; instead, a visual protocol description-system is used to specify the different parts of the serial communication.



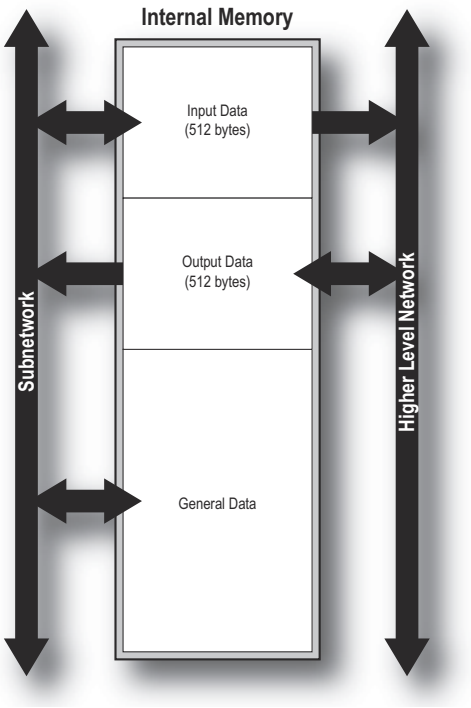
2.2 Data Exchange Model

Internally, the data exchanged on the subnetwork, and the data exchanged on the higher level network (i.e. EtherCAT), resides in the same memory.

This means that in order to exchange data with the subnetwork, the higher level network simply reads and writes data to memory locations specified using the Anybus Configuration Manager. The very same memory locations can then be exchanged on the subnetwork.

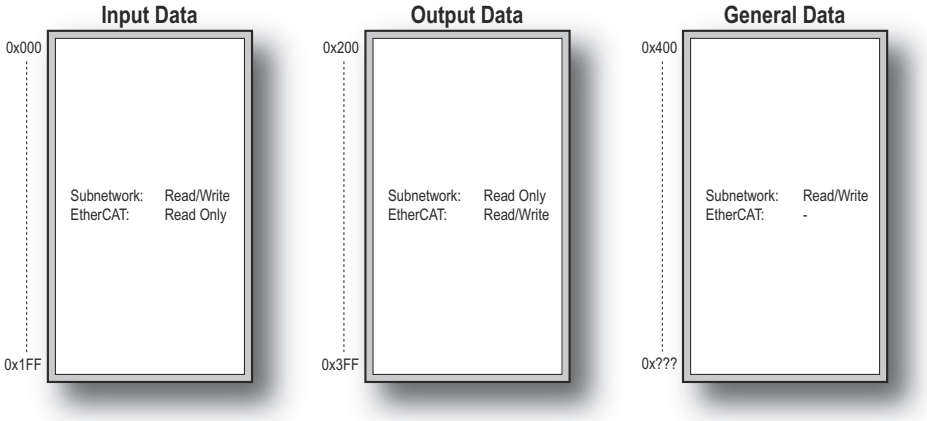
The internal memory buffer is divided into three areas based on their function:

- **Input Data (Up to 512 bytes)**
  This area can be read from the higher level network (i.e. by the EtherCAT master).
- **Output Data (Up to 512 bytes)**
  This area can be written to by the higher level network (i.e. by the EtherCAT master)
- **General Data (Up to 1024 bytes)**
  This area cannot be accessed from the higher level network, but can be used for transfers between individual nodes on the subnetwork, or as a general "scratch pad" for data. The actual size of this area depends on the amount of data that is exchanged on the subnetwork.



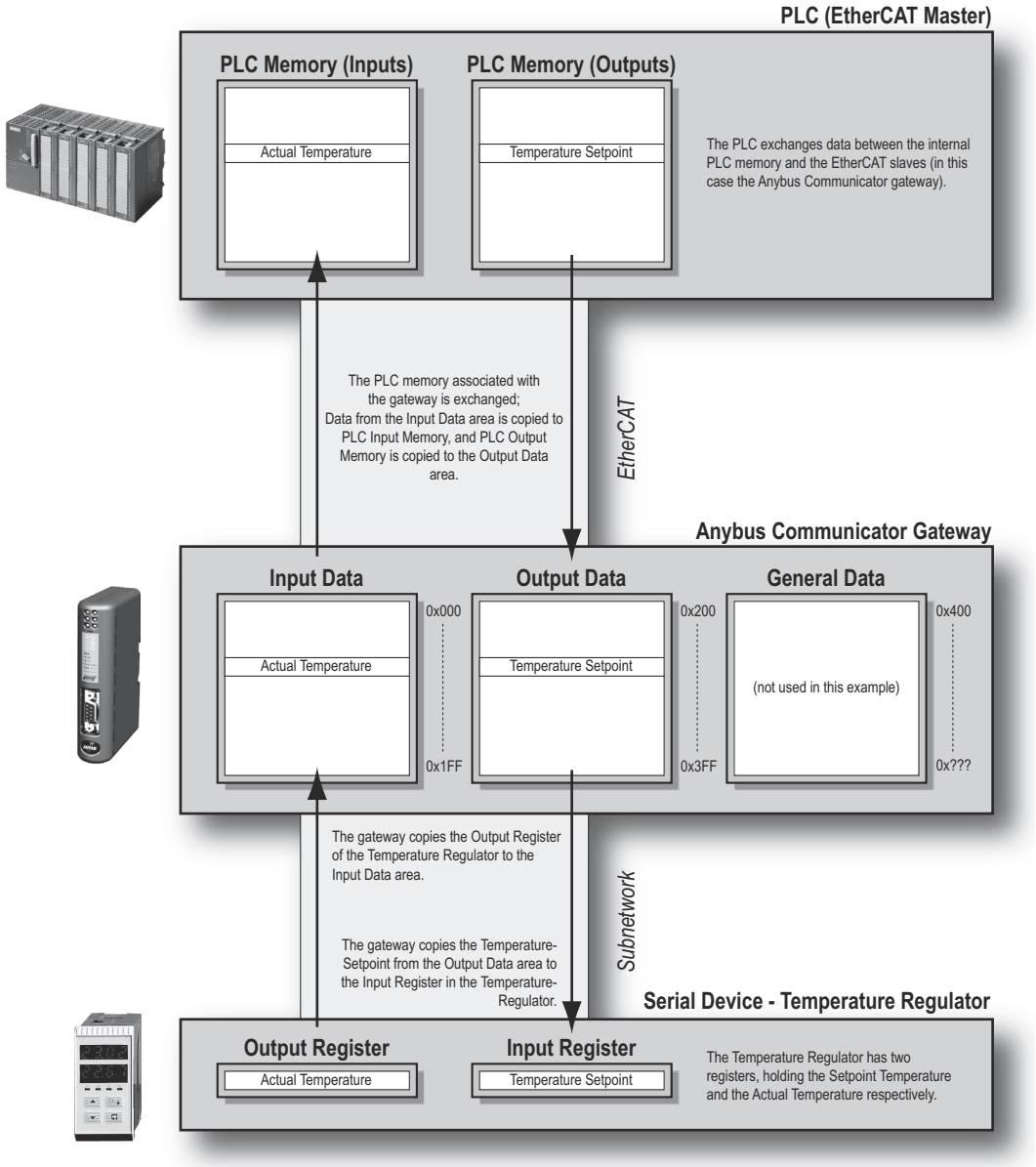
2.2.1 Memory Map

When building the subnetwork configuration using the Anybus Configuration Manager, the different areas described above are mapped to the memory locations (addresses) specified below.



2.2.2 Data Exchange Example

In the following example, a temperature regulator on the subnetwork exchanges information with a PLC on the higher level network, via the internal memory buffers in the gateway.


PLC (EtherCAT Master)
PLC Memory (Inputs)
PLC Memory (Outputs)
Actual Temperature
Temperature Setpoint
The PLC exchanges data between the internal PLC memory and the EtherCAT slaves (in this case the Anybus Communicator gateway).
The PLC memory associated with the gateway is exchanged; Data from the Input Data area is copied to PLC Input Memory, and PLC Output Memory is copied to the Output Data area.
EtherCAT
Anybus Communicator Gateway
Input Data
Output Data
General Data
0x000
0x1FF
0x200
0x3FF
0x400
0x???
Actual Temperature
Temperature Setpoint
(not used in this example)
The gateway copies the Output Register of the Temperature Regulator to the Input Data area.
The gateway copies the Temperature-Setpoint from the Output Data area to the Input Register in the Temperature-Regulator.
Subnetwork
Serial Device - Temperature Regulator
Output Register
Input Register
Actual Temperature
Temperature Setpoint
The Temperature Regulator has two registers, holding the Setpoint Temperature and the Actual Temperature respectively.

2.3 Subnetwork Protocol

2.3.1 Protocol Modes

The gateway features three distinct modes of operation regarding the subnetwork communication, called 'Master Mode', 'DF1 Master Mode' and 'Generic Data Mode'. Note that the protocol mode only specifies the basic communication model, not the actual subnetwork protocol.

- **Master Mode**

  In this mode, the gateway acts as a master on the subnetwork, and the serial communication takes place in a query-response fashion. The nodes on the network are not permitted to issue messages unless they have been addressed by the gateway first.

  See also "Master Mode" on page 19.

- **DF1 Master Mode**

  In this mode, the gateway acts as a master on the subnetwork, using the DF1 protocol. The serial communication takes place in a query-response fashion. For more information about this mode, see "DF1 Protocol Mode" on page 55.

- **Generic Data Mode**

  In this mode, there is no master-slave relationship between the subnetwork nodes and the gateway; any node on the subnetwork, including the gateway, may spontaneously produce or consume messages.

  See also "Generic Data Mode" on page 20.

2.3.2 Protocol Building Blocks

The following building blocks are used in Anybus Configuration Manager to describe the subnetwork communication. How these blocks apply to the two protocol modes will be described later in this document.

- **Node**

  A node represents a single device on the subnetwork. Each node can be associated with a number of transactions, see below.

- **Transaction**

  A 'transaction' represents a complete serial telegram, and consists of a number of frame objects (see below). Each transaction is associated with a set of parameters controlling how and when to use it on the subnetwork.

- **Commands**

  A 'command' is simply a predefined transaction stored in a list in the Anybus Configuration Manager. This simplifies common operations by allowing transactions to be stored and reused.

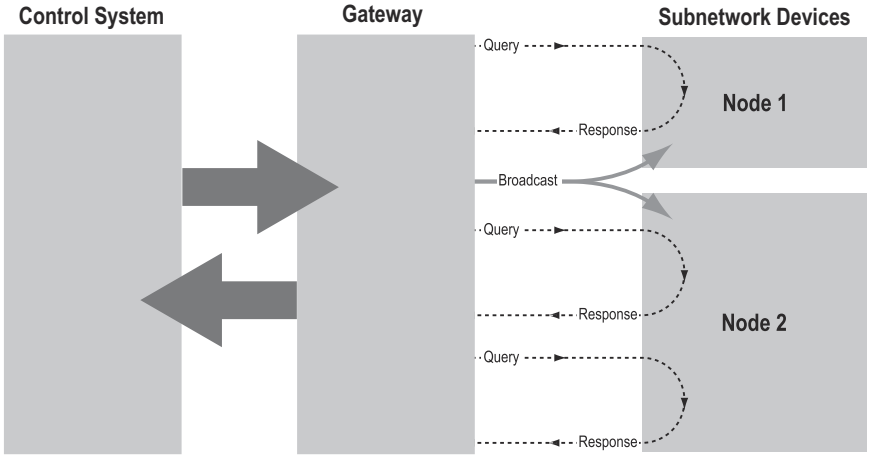
- **Frame Object**

  'Frame objects' are low level entities used to compose a transaction (see above). A frame object can represent a fixed value (a constant), a range of values (limit objects), a block of data or a calculated checksum.

2.3.3 Master Mode

In this mode, the communication is based on a query-response scheme; when the gateway issues a query on the subnetwork, the addressed node is expected to issue a response to that query. Nodes are not permitted issue responses spontaneously, i.e. without first receiving a query.

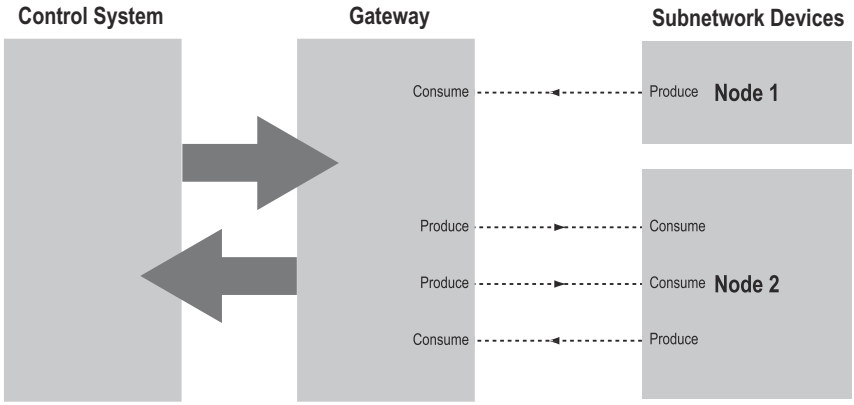
There is one exception to this rule; the broadcaster. Most protocols offer some way of broadcasting messages to all nodes on the network, without expecting them to respond to the broadcasted message. This is also reflected in the gateway, which features a dedicated broadcaster node.



In Master Mode, Anybus Configuration Manager comes preloaded with most commonly used Modbus RTU commands, which can conveniently be reached by right-clicking on a node in the Anybus Configuration Manager and selecting 'Insert New Command'. Note however that this does not in any way prevent other protocols based on the same query-response message-scheme to be implemented.

2.3.4 Generic Data Mode

In this mode, there is no master-slave relationship between the nodes on the subnetwork and the gateway. Any node, including the gateway itself, may spontaneously produce or consume a message. Nodes do not have to respond to messages, nor do they have to wait for a query in order to send one.



In the figure above, the gateway 'consumes' data that is 'produced' by a node on the subnetwork. This 'consumed' data can then be accessed from the higher level network. This also works the other way around; the data received from the higher level network is used to 'produce' a message on the subnetwork to be 'consumed' by a node.

2.3.5 DF1 Master Mode

Please refer to "DF1 Protocol Mode" on page 55.

2.4 EtherCAT Communication Properties

2.4.1 General

The EtherCAT interface acts as a full EtherCAT slave device with the following properties:

General Properties

- Full EtherCAT slave device
- 4 FMMU channels (can be used freely by the EtherCAT master for any purpose.)
- 4 SM channels
- 4kByte RAM
- Bit-oriented FMMU operation
- Position addressing, node addressing and logical addressing
- PDI Watchdog
- Output I/O Sync Manager Watchdog

Supported Features

- CANopen over EtherCAT
- DS301 v4.02 compliant
- Supports segmented SDO access
- Up to 512 bytes of cyclic data in each direction

2.4.2 Sync Managers

The gateway features four Sync Managers:

- **Sync Manager 0**
  Used for mailbox write transfers (Master to Slave).
  The gateway supports mailbox sizes of 50... 256 bytes (default = 192).
- **Sync Manager 1**
  Used for mailbox read transfers (Slave to Master).
  The gateway supports mailbox sizes of 50... 256 bytes (default = 192).
- **Sync Manager 2**
  Contains the RxPDOs specified by the PDO assignment.
  In practice, Sync Manager 2 holds the unmodified Output I/O data.
- **Sync Manager 3**
  Contains the TxPDOs specified by the PDO assignment.
  In practice, Sync Manager 3 holds the unmodified Input I/O data.

2.4.3 Data Representation

As mentioned previously, the gateway implements CANopen over EtherCAT. The object implementation is based on the DS301 communication profile.

Input and output data is mapped to dedicated objects in the manufacturer-specific range. Data declared as I/O data is exchanged by means of Process Data Objects (PDOs), while the remainder is exchanged through Service Data Objects (SDOs).

The PDO mapping is static and looks as follows:

PDO	Corresponding Object	Internal Memory
TxPDO 1A00h	Index 2000h, sub-index 1...128	Input Data, bytes 0... 127
TxPDO 1A01h	Index 2001h, sub-index 1...128	Input Data, bytes 128... 255
TxPDO 1A02h	Index 2002h, sub-index 1...128	Input Data, bytes 256... 383
TxPDO 1A03h	Index 2003h, sub-index 1...128	Input Data, bytes 384... 511
RxPDO 1600h	Index 2100h, sub-index 1...128	Output Data, bytes 0... 127
RxPDO 1601h	Index 2101h, sub-index 1...128	Output Data, bytes 128... 255
RxPDO 1602h	Index 2102h, sub-index 1...128	Output Data, bytes 256... 383
RxPDO 1603h	Index 2103h, sub-index 1...128	Output Data, bytes 384... 511

Note: The gateway will only map as many PDOs as required to hold the specified amount of I/O data.

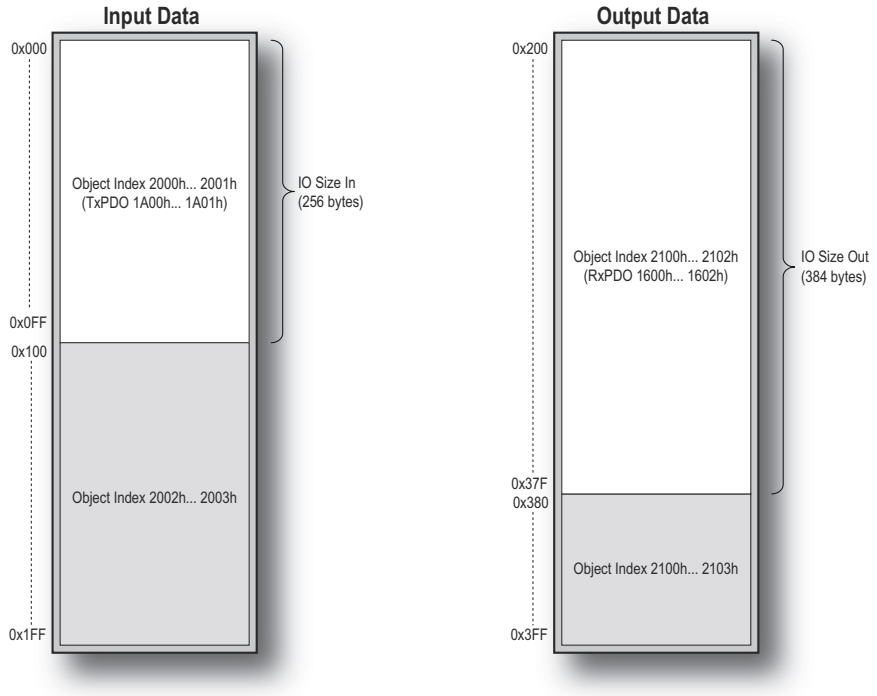
Example:

The following example illustrates how the internal memory buffers are represented on the EtherCAT network.

The I/O Sizes are set as follows:

IO Size In= 256 bytes (0x0100)
IO Size Out= 384 bytes (0x0180)

Resulting memory layout:



3. CANopen Object Dictionary Implementation

3.1 Standard Objects

3.1.1 General

The standard object dictionary is implemented in accordance with the DS301 specification (v4.02).

3.1.2 Object Entries

Index	Object Name	Sub-Index	Description	Type	Access	Notes
1000h	Device Type	00h	Device Type	U32	RO	0000 0000h (No profile)
1008h	Manufacturer device name	00h	Manufacturer device name	Visible string	RO	-
1018h	Identity object	00h	Number of entries	U8	RO	04h
		01h	Vendor ID	U32	RO	-
		02h	Product Code	U32	RO	
		03h	Revision Number	U32	RO	
		04h	Serial Number	U32	RO	
1600h ... 1603h	Receive PDO mapping	00h	Number of entries	U8	R	See 2-22 “Data Representation”
		01h... n	Mapped object #n	U32	R	
1A00h ... 1A03h	Transmit PDO mapping	00h	Number of entries	U8	R	See 2-22 “Data Representation”
		01h... Nn	Mapped object #n	U32	R	
1C00h	Sync Manager Communica-tion Type	00h	Number of entries	U8	R	04h
		01h	Mailbox wr	U8	R	01h
		02h	Mailbox rd	U8	R	02h
		03h	Process Data out	U8	R	03h
		04h	Process Data in	U8	R	04h
1C12h	Sync Manager Rx PDO Assign	00h	Number of entries [a]	U8	R	No. of assigned RxPDOs (0... 4)
		01h	Assigned RxPDO	U8	R	Assigned to RxPDO 1600h
		02h	Assigned RxPDO	U8	R	Assigned to RxPDO 1601h
		03h	Assigned RxPDO	U8	R	Assigned to RxPDO 1602h
		04h	Assigned RxPDO	U8	R	Assigned to RxPDO 1603h
1C13h	Sync Manager Tx PDO Assign	00h	Number of entries[a]	U8	R	No. of assigned TxPDOs (0... 4)
		01h	Assigned TxPDO	U8	R	Assigned to TxPDO 1A00h
		02h	Assigned TxPDO	U8	R	Assigned to TxPDO 1A01h
		03h	Assigned TxPDO	U8	R	Assigned to TxPDO 1A02h
		04h	Assigned TxPDO	U8	R	Assigned to TxPDO 1A03h

a. The number of entries equals the number of mapped PDOs, see “Data Representation” on page 22.

3.2 Manufacturer Specific Objects

3.2.1 Input Buffer

Index	Object Name	Sub-Index	Description	Type	Access	Notes
2000h	Inputs	00h	No. of entries	U8	RO	-
		01h	Input byte 0000	U8	RO	-
		02h	Input byte 0001			
		...	...			
		80h	Input byte 0127			
2001h	Inputs	00h	No. of entries	U8	RO	-
		01h	Input byte 0128	U8	RO	-
		02h	Input byte 0129			
		...	...			
		80h	Input byte 0255			
2002h	Inputs	00h	No. of entries	U8	RO	-
		01h	Input byte 0256	U8	RO	-
		02h	Input byte 0257			
		...	...			
		80h	Input byte 0383			
2003h	Inputs	00h	No. of entries	U8	RO	-
		01h	Input byte 0384	U8	RO	-
		02h	Input byte 0385			
		...	...			
		80h	Input byte 0511			

Note: The gateway will only create the number of objects needed to hold the subnetwork configuration.

See also...

- "Data Representation" on page 22

3.2.2 Output Buffer

Index	Object Name	Sub-Index	Description	Type	Access	Notes
2100h	Outputs	00h	No. of entries	U8	RO	-
		01h	Output byte 0000	U8	R(W)	-
		02h	Output byte 0001			
		...	...			
		80h	Output byte 0127			
2101h	Outputs	00h	No. of entries	U8	RO	-
		01h	Output byte 0128	U8	R(W)	-
		02h	Output byte 0129			
		...	...			
		80h	Output byte 0255			
2102h	Outputs	00h	No. of entries	U8	RO	-
		01h	Output byte 0256	U8	R(W)	-
		02h	Output byte 0257			
		...	...			
		80h	Output byte 0383			
2103h	Outputs	00h	No. of entries	U8	RO	-
		01h	Output byte 0384	U8	R(W)	-
		02h	Output byte 0385			
		...	...			
		80h	Output byte 0511			

Note 1: For consistency reasons, data declared as I/O data will be read-only.

Note 2: The gateway will only create the number of objects needed to hold the subnetwork configuration.

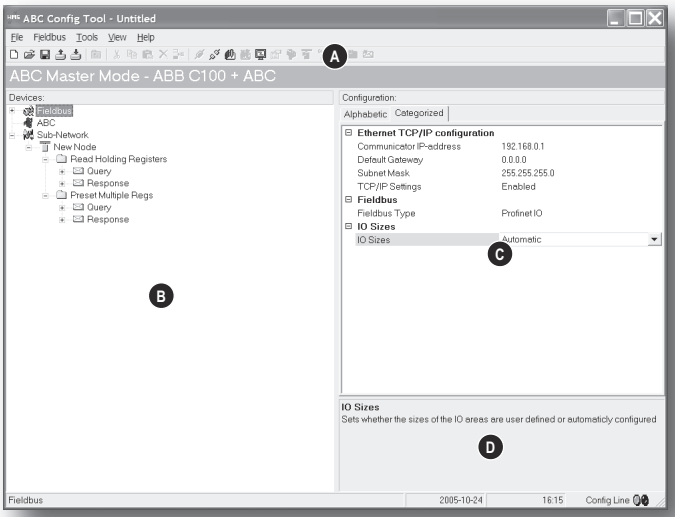
See also...

- "Data Representation" on page 22

4. Navigating the Anybus Configuration Manager

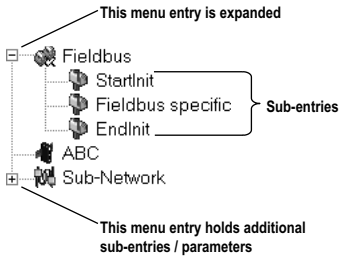
4.1 Main Window

The main window in the Anybus Configuration Manager can be divided into 4 sections as follows:



- **A: Pull-down Menus & Tool Bar**

  The second drop-down menu from the left will change depending on the current context. The Tool Bar provides quick access to the most frequently used functions.



- **B: Navigation Section**

  This section is the main tool for selecting and altering different levels of the subnetwork configuration.

  Entries preceded by a '+' holds further configuration parameters or 'sub menus'. To gain access to these parameters, the entry must be expanded by clicking '+'.

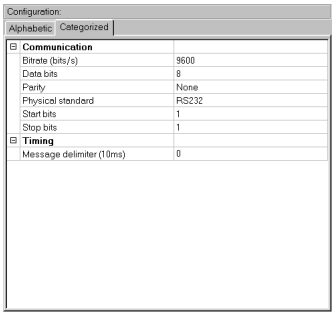
  There are three main levels in the navigation window, namely Fieldbus, ABC and subnetwork.

  Right-clicking on entries in this section brings out additional selections related to that particular entry.

- **C: Parameter Section**

  This section holds a list of parameters or options related to the currently selected entry in the Navigation Section.

  The parameter value may be specified either using a selection box or manually, depending on the parameter itself. Values can be specified in decimal form (e.g. '42'), or in hexadecimal format (e.g. '0x2A').



Parameter Section

- **D: Information Section**

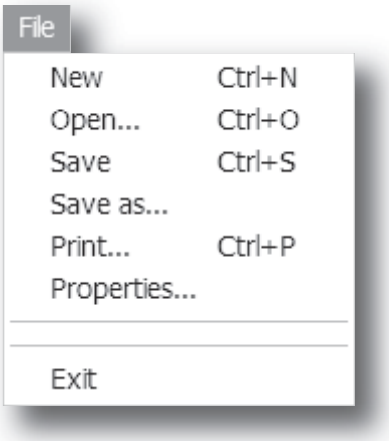
  This section holds information related to the currently selected parameter.

Information Section

4.1.1 Pull-down Menu

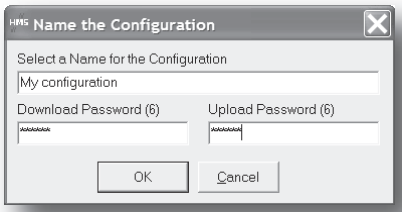
File

This menu features the following entries:



- **New**
  Create a new configuration.
  See also "Configuration Wizards" on page 67.
- **Open...**
  Open a previously created configuration.
- **Save**
  Save the current configuration.
- **Save As...**
  Save the current configuration under a new name.
- **Print...**
  Send details about the current configuration to a printer.
- **Properties...**
  This brings out the following window:

Item	Description
Select a Name for the Configuration	A name for the configuration may be entered here
Download Password(6)	These fields can be used to password-protect the configuration in the gateway.
Upload Password(6)	

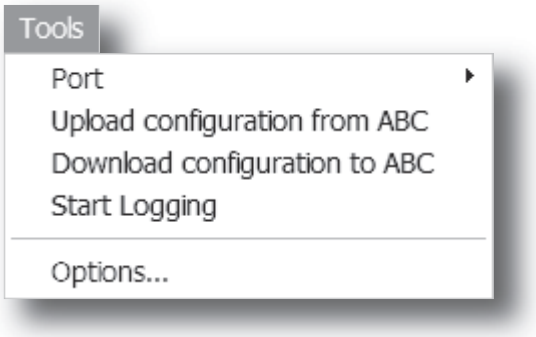


CAUTION: Always keep a copy of the password in a safe place. A lost password cannot be retrieved!

- **Exit**
  Close the Anybus Configuration Manager.

Tools

This menu features the following entries:



- **Port**

  This entry selects the COM-port used for the configuration of the gateway.

- **Upload configuration from ABC**

  Upload the configuration from the gateway to the Anybus Configuration Manager.

- **Download configuration to ABC**

  Download the current configuration into the gateway.

- **Start Logging**

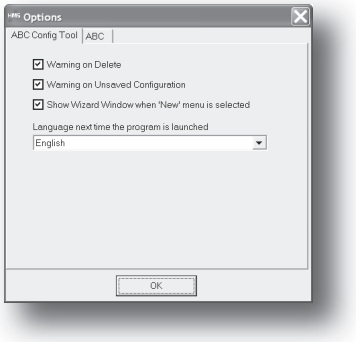
  Start the Data Logger (see "Data Logger" on page 67).

  Note that when the Data Logger is active, this menu entry is changed to 'Stop Logging'.

- **Options**

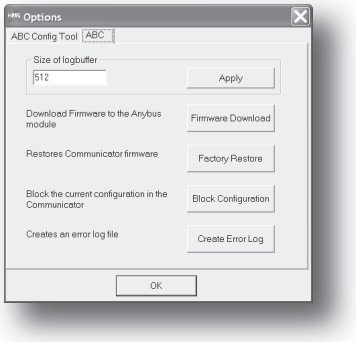
  This will bring out the following window:

Item	Description
Warning on Delete	A confirmation dialog is displayed each time something is deleted.
Warning on unsaved data	A confirmation dialog is displayed when closing the Anybus Configuration Manager with unsaved data.
Show Wizard when "New" menu is selected	The Wizard is displayed each time a new configuration is created.
Language next time the program is launched	Selects which language to use. The new setting will be active the next time the program is launched.



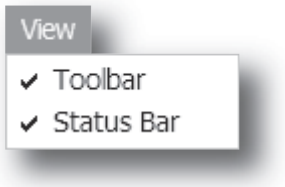
Selecting the 'ABC'-tab will reveal additional properties:

Item	Description
Size of logbuffer	By default, the Data Logger can log up to 512 entries in each direction. If necessary, it is possible to specify a different number of entries (valid settings range from 1...512). Click 'Apply' to validate the new settings. See also "Data Logger" on page 67.
Firmware Download	Download firmware to the embedded fieldbus interface. **Warning: Use with caution.**
Factory Restore	Restores the gateway firmware to it's original state (does not affect the embedded fieldbus interface).
Block Configuration	When selected, the downloaded configuration will not be executed by the gateway. **Warning: Use with caution.**
Create Error log	Creates an error log file



View

This menu features the following entries:



- **Toolbar**

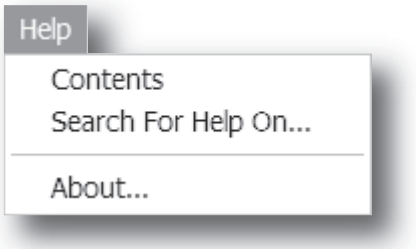
  This entry enables/disables the toolbar icons at the top of the main window.

- **Status Bar**

  This entry enables/disables the status bar at the bottom of the main window.

Help

This menu features the following entries:



- **Contents**

  Display the table of contents of the online help system.

  Note: At the time of writing, no online help system exists.

- **Search For Help On...**

  Search for a particular topic in the online help system.

  Note: At the time of writing, no online help system exists.

- **About...**

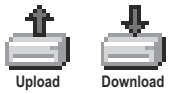
  Display general information about the gateway and the current build of Anybus Configuration Manager.

4.1.2 Toolbar Icons

The toolbar features icons for the most commonly used functions.

- **New, Open & Save**
  See "File" on page 27.

- **Upload from ABC & Download to ABC**
  See "Tools" on page 28.



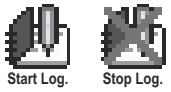
- **Up one Level**
  Clicking on this icon will move the selection in the navigation section.

- **Cut, Copy, Paste, Delete, Insert**
  These icons are used for common editing functions in the navigation section.

- **Connect**
  Clicking on this icon will cause the Anybus Configuration Manager to attempt to connect to the gateway.

- **Disconnect**
  Clicking on this icon will cause the Anybus Configuration Manager to disconnect from the gateway.

- **Start Logging & Stop Logging**
  See "Tools" on page 28 & "Data Logger" on page 67.

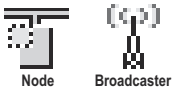


- **Subnetwork Monitor**
  Clicking on this icon will launch the subnetwork Monitor (see "Subnetwork Monitor" on page 62).

- **Add Command**
  This icon is used to add commands to the currently selected node.

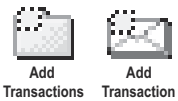
- **Add Mailbox**
  (Advanced functionality, see "Mailbox Editor" on page 76)

- **Add Node & Add Broadcaster**
  These icons are used to add nodes to the configuration.



- **Node Monitor**
  Clicking on this icon will launch the Node Monitor (see "Node Monitor" on page 63)

- **Add Transaction(s)**
  These icons are used to add transactions to the currently selected node.



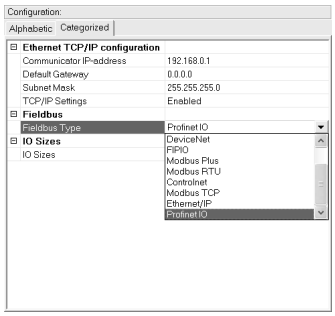
5. Basic Settings

5.1 Fieldbus Settings

(Select 'Fieldbus' in the Navigation Section to gain access to the parameters described in this section).

Fieldbus Type

Since the Anybus Configuration Manager supports a wide range of networking systems, make sure that this parameter is set to 'EtherCAT'.



Fieldbus Type

IO Sizes

These parameters specify how data from the internal memory buffer shall be exchanged on EtherCAT. This can either be handled automatically by the gateway, or specified manually.

- **Automatic**

  All data will be treated as cyclical I/O, i.e. it will be exchanged through Process Data Objects (PDO).

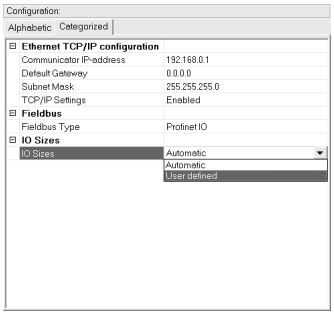
  (see also "Data Representation" on page 22)

- **User defined**

  Additional parameter properties appear; 'IO Size In' and 'IO Size Out'. The specified amount, starting at address 0x0000 of the respective memory buffers, will be exchanged as cyclical I/O, i.e. through Process Data Objects (PDO). The memory area can be read but not written by Service Data Objects (SDO).

  The remainder will be exchanged as acyclical I/O through Service Data Objects (SDO).

  (see also "Data Representation" on page 22)



IO Sizes

5.2 ABC Parameters

(Select 'ABC' in the Navigation Section to gain access to the parameters described in this section).

Interface

Currently, only serial communication is supported.

Status / Control Word

(See "Control and Status Registers" on page 71).

Value	Description
Enabled	Enable the Control and Status Registers. The 'Data Valid'-bit in the Control Register must be set to start the subnetwork communication.
Enabled but no startup lock	This setting is similar to 'Enabled', except that the control system is not required to set the 'Data Valid'-bit to start the subnetwork communication.
Disabled	This setting completely disables the Control and Status Registers.

Module Reset

This parameter specifies how the gateway will behave in the event of a fatal error.

Value	Description
Enabled	The gateway will be restarted, and no error will be indicated to the user.
Disabled	The gateway will halt and indicate an error.

Protocol Mode

This parameter specifies which protocol mode to use for the subnetwork.

Value	Description
Generic Data Mode	This mode is primarily intended for Produce & Consume-based protocols, where there are no Master-Slave relationship between the gateway and the nodes on the subnetwork.
Master Mode	This mode is intended for 'Query & Response'-based protocols, where a single Master exchanges data with a number of Slaves.
DF1	This mode is intended for the DF1 protocol. The Anybus Communicator can only be configured as a Master with half-duplex communication. **Note:** This is the only mode available if you intend to configure an ABC module for DF1.

See also "Protocol Modes" on page 18.

Statistics

The Transmit- and Receive Counters indicate how many transactions that have successfully been exchanged on the subnetwork. This feature is primarily intended for debugging purposes.

- **Receive Counter Location**
  Specifies the location of the Receive Counter in the internal memory buffer.
- **Transmit Counter Location**
  Specifies the location of the Transmit Counter in the internal memory buffer.

Both counters are enabled by setting 'Statistics' to 'Enabled'.

5.3 Subnetwork Parameters

(To gain access to the parameters described in this section, select 'Subnetwork' in the Navigation Section).

Communication

These parameters specify the actual communication settings used for the subnetwork.

Parameter	Description	Master Mode and Generic Mode
Bit rate (baud rate)	Selects the bit rate	1200 2400 4800 9600 19200 35700 38400 57600
Data bits	Selects the number of data bits	7, 8
Parity	Selects the parity mode	None, Odd, Even
Physical standard	Selects the physical interface type	RS232, RS422, RS485
Start bits	Number of start bits.	1
Stop bits	Number of stop bits.	1, 2

Start- and End Character

Note: These parameters are only available in Generic Data Mode.

Start and end characters are used to indicate the beginning and end of a serial message. For example, a message may be initiated with <ESC> and terminated with <LF>. In this case, the Start character would be 0x1B (ASCII code for <ESC>) and the End character 0x0A (ASCII code for <LF>)

Parameter	Description	Valid settings
End Character Value	End character for the message, ASCII	0x00 - 0xFF
Use End Character	Determines if the End character shall be used or not	Enable / Disable
Start Character Value	Start character for the message, ASCII	0x00 - 0xFF
Use Start Character	Determines if the Start character shall be used or not	Enable / Disable

Timing (Message Delimiter)

The parameters in this category differs slightly between the different protocol modes.

- **Master Mode**

  The Message Delimiter specifies the time that separates two messages in steps of 10ms. If set to 0 (zero), the gateway will use the standard Modbus delimiter of 3.5 characters (the actual number of ms will be calculated automatically based on the currently used communication settings).

- **Generic Data Mode**

  The Message Delimiter specifies the time that separates two messages in steps of 10µs.

6. Nodes

6.1 General

In Anybus Configuration Manager, a node represents a single device on the network. While the gateway doesn't feature a scanlist in the traditional sense, all nodes, and their transactions, will be processed in the order they have been defined in the Anybus Configuration Manager.

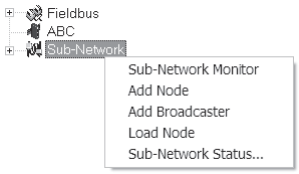
The maximum number of nodes that can be created in the Anybus Configuration Manager is 31.

6.2 Adding & Managing Nodes

(Right-click on 'Sub Network' in the Navigation Section to gain access to these functions)

Function	Description
Paste	Paste a node from the clipboard
Subnetwork Monitor	Launch the subnet monitor ("Subnetwork Monitor" on page 62)
Add Node	Add a node to the configuration
Add Broadcaster[a]	Add a broadcaster node to the configuration
Load Node	Add a previously saved node
Subnetwork Status...	View diagnostic information about the subnetwork

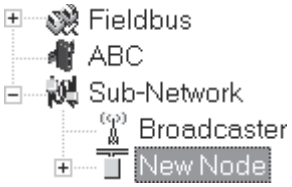
a. This function is only available in Master Mode.



6.3 Node Parameters

6.3.1 Master Mode and Generic Data Mode

(To gain access to the parameters described in this section, select a node in the Navigation Section).



Parameter	Description
Slave Address	The value entered here may be used to set the node address in certain commands. For more information, see "The Command Editor" on page 51.

7. Transactions

7.1 General

As mentioned previously, transactions are representations of the actual serial telegrams exchanged on the serial subnetwork. While the gateway doesn't feature a scanlist in the traditional sense, all nodes, and their transactions, will be processed in the order they have been defined in the Anybus Configuration Manager.

Transactions are handled slightly differently in the three protocol modes:

- **Master Mode**

  For regular nodes, transactions always come in pairs; a query and a response. The query is issued by the gateway, while responses are issued by the slaves on the subnetwork. The Broadcaster can only send transactions.

- **Generic Data Mode**

  Transactions can be added as desired for both directions. Transactions sent to the subnetwork are called 'Transaction Produce', and transactions issued by other nodes are called 'Transaction Consume'.

- **DF1 Master Mode**

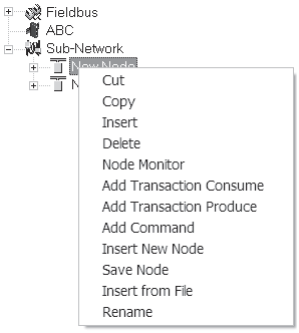
  Please refer to "DF1 Protocol Mode" on page 55.

Theoretically, the gateway supports up to 150 transactions. The actual number may however be less depending on the memory requirements of the defined transactions.

7.2 Adding & Managing Transactions

(Right-click on a node in the Navigation Section to gain access to these functions)

Function	Description
Cut	Cut a node to the clipboard
Copy	Copy a node to the clipboard
Insert	Insert a node from the clipboard
Delete	Delete a node
Node Monitor	Launch the node monitor (“Node Monitor” on page 63)
Add Transaction(s)[a]	On regular nodes, this adds a Query and a Response. The two transactions will be grouped in order to increase readability. On the Broadcaster, a single transaction will be added.
Add Transaction Consume[b]	Add a ‘Consume’-transaction
Add transaction Produce[b]	Add a ‘Produce’-transaction
Add Command	Add predefined transactions to the node
Insert New Node	Insert a new node above the currently selected one
Save Node	Save the selected node
Insert from File	Insert a previously saved node above the currently selected node
Rename	To increase readability, each node can be given a unique name using this function



a. Only available in Master Mode
b. Only available in Generic Data Mode

7.3 Transaction Parameters (Master Mode)

7.3.1 Parameters (Query & Broadcast)

(To gain access to these parameters, select a Query- or Broadcast- transaction in the Navigation Section)

Parameter	Description
Minimum time between broadcasts (10 ms)	This parameter specifies how long the gateway shall wait after transmitting a broadcast transaction before processing the next entry in the scanlist. The value should be set high enough to allow the slave devices time to finish the handling of the broadcast. The entered value is multiplied by 10. For instance, an entered value of 5 results in 50 ms. **Note:** This setting is only relevant for the Broadcaster node.
Offline options for fieldbus	This parameter specifies the action to take for this transaction if the higher level network goes offline. This affects the data that is sent to the subnetwork. • **Clear** - The data destined for the slave-devices is cleared (set to zero) • **Freeze** - The data destined for the slave-device is frozen • **NoScanning** -The updating of the subnetwork is stopped
Offline options for subnetwork	This parameter specifies the action to take for this transaction if the subnetwork goes offline. This affects the data that is reported to the control system. • **Clear** - Data is cleared (0) on the higher level network if the subnetwork goes offline • **Freeze** - Data is frozen on the higher level network if the subnetwork goes offline
Reconnect time (10 ms)	This parameter specifies how long the gateway shall wait before attempting to reconnect a disconnected node. A node will be disconnected in case the maximum number of retries (below) has been reached. The entered value is multiplied by 10. For instance, an entered value of 5 results in 50 ms. **Note:** This setting is not relevant for the Broadcaster node.
Retries	This parameter specifies how many times a timeout may occur in sequence before the node is disconnected.
Timeout time (10 ms)	This parameter specifies how long the gateway will wait for a response from a node. If this time is exceeded, the gateway will retransmit the Query until the maximum number of retries (see above) has been reached. The entered value is multiplied by 10. For instance, an entered value of 5 results in 50 ms.
Trigger byte address	This parameter specifies the location of the trigger byte in internal memory (only relevant when 'Update mode' is set to 'Change of state on trigger'). Valid settings range from 0x200... 0x3FF and 0x400... 0xNNN
Update mode	This parameter is used to specify when the transaction shall be sent to the slave: • **Cyclically** The transaction is issued cyclically at the interval specified in the 'Update time' parameter. • **On data change** The data area is polled for changes at the time interval defined by Update time. A transaction is issued when a change in data is detected. • **Single shot** The Query is issued once at start up. • **Change of state on trigger** The Query is issued when the trigger byte value has changed. This feature enables the control system to notify the gateway when to issue a particular Query. To use this feature correctly, the control system must first update the data area associated with the Query/transaction, then increase the trigger byte by one. The location of the trigger byte is specified by the 'Trigger byte address' parameter.

Parameter	Description
Update time (10 ms)	This parameter specifies how often the transaction will be issued in steps of 10 ms (only relevant when 'Update mode' is set to 'Cyclically'). The entered value is multiplied by 10. For instance, an entered value of 5 results in 50 ms.

7.3.2 Parameters (Response)

(To gain access to these parameters, select a Response-transaction in the Navigation Section)

Parameter	Description
Trigger byte	This parameter is used to enable/disable the trigger functionality for the response. If enabled, the gateway will increase the trigger byte by one when the gateway receives new data from the subnetwork. This can be used to notify the control system of the updated data. The location of the trigger byte is specified by the 'Trigger byte address' parameter below.
Trigger byte address	This parameter specifies the location of the trigger byte in the internal memory buffer. Valid settings range from 0x000... 0x1FF and 0x400... 0xNNN

7.4 Transaction Parameters (Generic Data Mode)

7.4.1 Produce-Transactions

(To gain access to these parameters, select a Produce Transaction in the Navigation Section)

Parameter	Description
Offline options for fieldbus	This parameter specifies the action to take for this transaction if the higher level network goes offline. This affects the data that is sent to the subnetwork. • **Clear** Data is cleared (0) on the subnetwork if the higher level network goes offline • **Freeze** Data is frozen on the subnetwork if the higher level network goes offline • **NoScanning** Stop subnet scanning for this transaction if the higher level network goes offline
Update mode	The update mode for the transaction: • **Cyclically** The transaction is sent cyclically at the interval specified in the 'Update Time'-parameter. • **On data change** The data area is polled for changes at the time interval defined by Update time. A transaction is issued when a change in data is detected. • **Single shot** The transaction is sent once at startup. • **Change of state on trigger** The transaction is sent when the trigger byte has changed. This feature enables the control system to notify the gateway when to issue a particular transaction. To use this feature correctly, the control system must first update the data area associated with the transaction, then increase the trigger byte by one. The location of the trigger byte is specified by the 'Trigger byte address' parameter.
Update time (10 ms)	This parameter specifies how often the transaction will be issued in steps of 10ms (only relevant when 'Update mode' is set to 'Cyclically'). The entered value is multiplied by 10. For instance, an entered value of 5 results in 50 ms.

Parameter	Description
Trigger byte address	This parameter specifies location of the trigger byte in the internal memory buffer. If 'Update mode' is set to 'Change of state on trigger', the memory location specified by this parameter is monitored by the gateway. Whenever the trigger byte is updated, the gateway will produce the transaction on the subnetwork. This way, the control system can instruct the gateway to produce a specific transaction on the subnetwork by updating the corresponding trigger byte. The trigger byte should be incremented by one for each activation. Please note that the trigger byte address must be unique to each transaction. It can not be shared by two or more transactions. **Note:** This parameter has no effect unless the 'Update mode' parameter is set to 'Change of state on trigger'. Valid settings range from 0x200... 0x3FF and 0x400... 0xNNN

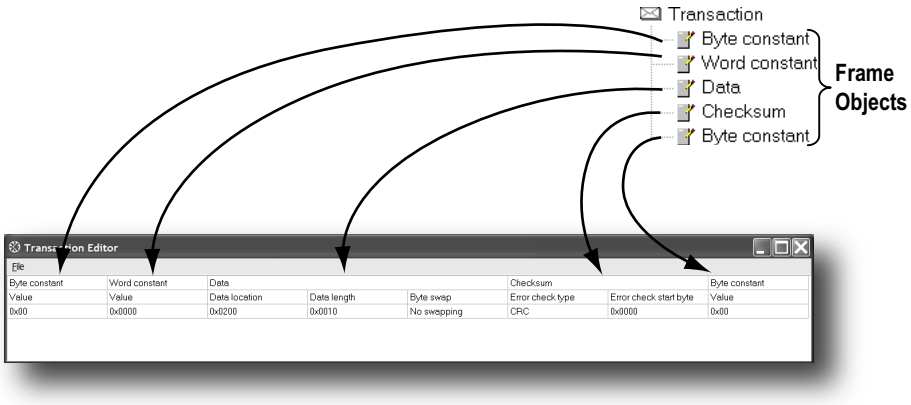
7.4.2 Consume-Transactions

(To gain access to these parameters, select a Consume Transaction in the Navigation Section)

Parameter	Description
Offline options for subnetwork	This parameter specifies the action to take for this transaction if the subnetwork goes offline. This affects the data that is sent to the higher level network. • **Clear** Data is cleared (0) on the higher level network if the subnetwork goes offline • **Freeze** Data is frozen on the higher level network if the subnetwork goes offline
Offline timeout time (10 ms)	This parameter specifies the maximum allowed time between two incoming messages in steps of 10ms. If this time is exceeded, the subnetwork is considered to be offline. A value of 0 disables this feature, i.e. the subnetwork can never go offline. The entered value is multiplied by 10. For instance, an entered value of 5 results in 50 ms.
Trigger byte	• **Enable** Enables the trigger byte. The location of the trigger byte must be specified in the 'Trigger byte address' (below). The trigger byte value will be increased each time a valid transaction has been consumed by the gateway. The trigger byte will also be increased if the offline option is set to "Clear" and the offline timeout time value is reached. This feature enables the control system to be notified each time new data has been consumed on the subnetwork. • **Disable** Disables the trigger byte functionality.
Trigger byte address	This parameter specifies the location of the trigger byte in the internal memory buffer. Valid settings range from 0x000... 0x1FF and 0x400... 0xNNN. Please note that the trigger byte address must be unique to each transaction. It can not be shared by two or more transactions.

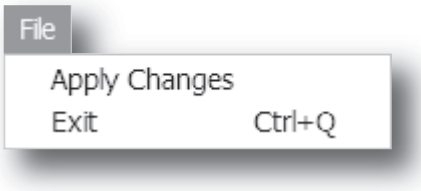
7.5 Transaction Editor

The Transaction Editor can be used to edit the individual frame objects of a transaction. The same settings are also available in the parameter section of the main window, however the Transaction Editor presents the frame objects in a more visual manner.


Transaction
Byte constant
Word constant
Data
Checksum
Byte constant
Frame Objects
Transaction Editor
File
Byte constant | Word constant | Data | | | Checksum | Byte constant
Value | Value | Data location | Data length | Byte swap | Error check type | Error check start byte | Value
0x00 | 0x0000 | 0x0200 | 0x0010 | No swapping | CRC | 0x0000 | 0x00

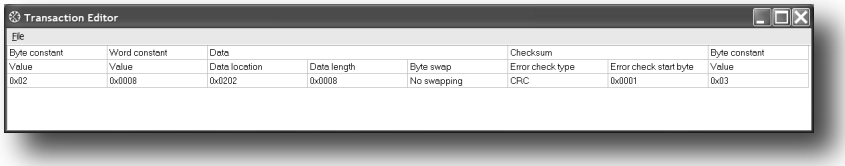
To edit the value of a parameter, click on it and enter a new value using the keyboard. When editing transactions which are based on predefined commands, certain parts of the transaction may not be editable.

The File menu features the following entries:



- **Apply Changes**
  This will save any changes and exit to the main window.
- **Exit**
  Exit without saving.

Example:


Transaction Editor
File
Byte constant | Word constant | Data | | | Checksum | Byte constant
Value | Value | Data location | Data length | Byte swap | Error check type | Error check start byte | Value
0x02 | 0x0008 | 0x0202 | 0x0008 | No swapping | CRC | 0x0001 | 0x03

The transaction created in this example are built up as follows:

The first byte holds the STX (0x02) followed by two bytes specifying the length of the data field (in this case 8). The next 8 bytes are data and since this is a 'query'-transaction, the data is to be fetched from the Output Area which starts at address location 0x202. No swapping will be performed on the data. This is followed by a two-byte checksum. The checksum calculation starts with the second byte in the transaction.

The transaction ends with a byte constant, the ETX (0x03).

8. Frame Objects

8.1 General

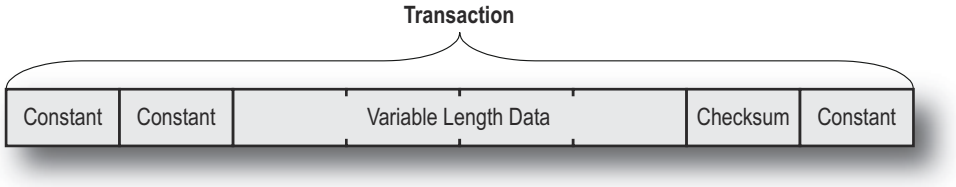
Each transaction consists of Frame Objects which makes up the serial telegram frame. Each Frame Object specifies how the gateway shall interpret or generate a particular part of the telegram.

There are 5 types of frame objects, which are described in detail later in this chapter:

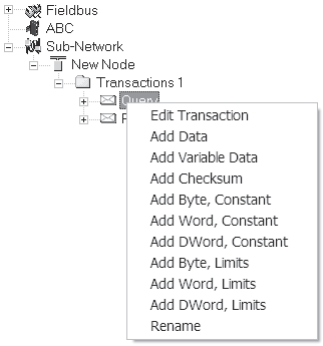
- Constant Objects
- Limit Objects
- Data Objects
- Variable Data Objects
- Checksum Objects

Example:

The following Transaction consists of several frame objects; three constants, a data object, and a checksum object.

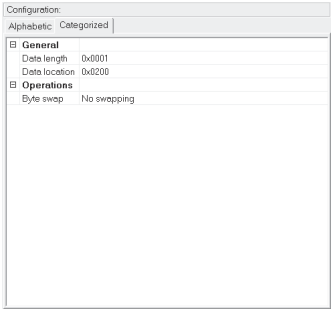


8.2 Adding and Editing Frame Objects



To add a frame object to a Transaction, right-click on the Transaction in the Navigation Section and select one of the entries in the menu that appears.

The entry called 'Transaction Editor' will launch the Transaction Editor, which is used to edit transactions and frame objects in a more visual manner. For more information, see "Transaction Editor" on page 42.



Data Object, Parameters

To edit parameters associated with a particular frame object, select the frame object in the Navigation Section. The settings for that frame object will be displayed in the Parameter Section.

It is also possible to edit the frame objects in a transaction in a more visual manner using the Transaction Editor, see "Transaction Editor" on page 42

8.3 Constant Objects (Byte, Word, Dword)

Constant Objects have a fixed value and come in three sizes:

- **Byte**
  8 bits
- **Word**
  16 bits
- **Dword**
  32 bits

Constants are handled differently depending on the direction of the transaction:

- **Produce/Query Transactions**
  The gateway will send the value as it is without processing it.
- **Consume/Response Transactions**
  The gateway will check if the received byte/word/dword matches the specified value. If not, the message will be discarded.

To set the value of the object, select it in the Navigation Section and enter the desired value in the Parameter section.

Parameter	Description
Value	Constant value

8.4 Limit Objects (Byte, Word, Dword)

Limit Objects have a fixed range and come in three sizes:

- **Byte**
  8 bits
- **Word**
  16 bits
- **Dword**
  32 bits

Limit Objects are handled differently depending on the direction of the transaction:

- **Produce/Query Transactions**
  This object shall not be used for such transactions (value will be undefined).
- **Consume/Response Transactions**
  The gateway will check if the received byte/word/dword fits inside the specified boundaries. If not, the message will be discarded.

There are 3 types of interval objects:

- **Byte**
  8 bit interval
- **Word**
  16 bit interval
- **Dword**
  32 bit interval

To set the range of the object, select it in the Navigation Section and enter the desired range in the Parameter section as follows:

Parameter	Description
Maximum Value	This is the largest allowed value for the range. Range:0x00... 0xFFh(byte) 0x0000... 0xFFFFh(word) 0x00000000... 0xFFFFFFFFh(dword) **Note:** Value must be larger than the Minimum Value (below)
Minimum Value	This is the smallest allowed value for the range. Range:0x00... 0xFEh(byte) 0x0000... 0xFFFEh(word) 0x00000000... 0xFFFFFFFEh(dword) **Note:** Value must be less than the Maximum Value (above)

8.5 Data Object

Data Objects are used to represent raw data as follows:

- **Produce/Query Transactions**
  The specified data block is forwarded from the higher level network to the subnetwork.
- **Consume/Response Transactions**
  The specified data block is forwarded from the subnetwork to the higher level network.

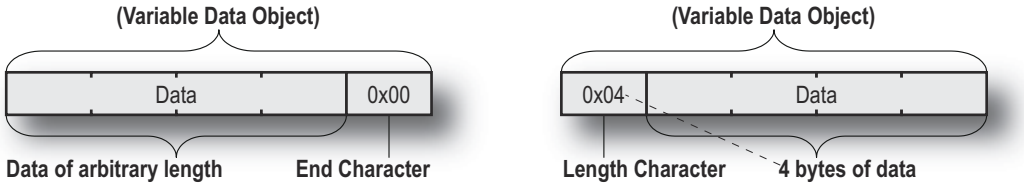
To specify the properties of the object, select it in the Navigation Section and enter the desired settings in the Parameter section as follows:

Parameter	Description
Byte Swapping	• **No Swapping** No swapping is performed on the data • **Swap 2 bytes** A, B, C, D becomes B, A, D, C • **Swap 4 bytes** A, B, C, D becomes D, C, B, A
Data Length	The length of the data block, in bytes. In case of a Response or Consume transaction, incoming messages where the data size differs from the value specified here will be discarded. Maximum data length allowed for one frame is 300 bytes.
Data Location	The location of the data block in the internal memory buffer

8.6 Variable Data Object

Note: Only one Variable Data Object is permitted for each transaction.

This object is similar to the Data Object, except that it has no predefined length. Instead, an End or Length-character specifies the size of the data block as follows:



- **Produce/Query Transactions**
  The specified data block will be forwarded from the higher level network to the subnetwork. The control system must supply an End- or Length-character in order for the gateway to know the size of the data block.
  The End- or Length-character itself may either be forwarded to the subnetwork or discarded.
- **Consume/Response Transactions**
  The specified data block is forwarded from the subnetwork to the higher level network. The End- or Length-character will be generated by the gateway automatically (if applicable).
  The End- or Length-character itself may either be forwarded to the higher level network or discarded.

To specify the properties of the object, select it in the Navigation Section enter the desired settings in the Parameter section as follows:

Parameter	Description
Byte Swapping	• **No Swapping** No swapping will be performed on the data • **Swap 2 bytes** A, B, C, D becomes B, A, D, C • **Swap 4 bytes** A, B, C, D becomes D, C, B, A
Fill unused bytes	• **Enabled**[a] Fill unused data with the value specified in 'Filler byte'. • **Disabled** Don't fill
Filler byte	Filler byte value. Only used if 'Fill unused bytes' has been enabled.
Data Location	The offset in the internal memory buffer where the data shall be read from / written to
Object Delimiter	• **Length Character** Length character is visible in the internal memory buffer but *not* on the subnetwork • **Length Character Visible** The length character is visible both in the internal memory buffer *and* on the subnetwork. • **End Character** The end character is visible in the internal memory buffer but *not* on the subnetwork. • **End Character Visible** The end character is visible both in the internal memory buffer *and* on the subnetwork • **No Character**[a] No End- or Length-character is generated in the internal memory buffer.
End Character Value	End Character value[b]
Maximum Data Length	The maximum allowed length (in bytes) of the variable data object. If the actual length of the data exceeds this value, the message will be discarded. The value must not exceed 300 bytes, which is the maximum data length allowed for one frame.

a. Only relevant for Consume/Response transactions
b. Only used if 'Object Delimiter' is set to 'End Character' or 'End Character Visible'

8.7 Checksum Object

Most serial protocols features some way of verifying that the data has not been corrupted during transfer. The Checksum Object calculates and includes a checksum in a transaction.

Parameter	Description
Error Check Start byte	This parameter specifies the byte offset in the transaction to start checksum calculations on
Error Check Type	This parameter specifies which type of algorithm to use: • **CRC (2 bytes)** CRC-16 with 0xA001 polynome (Modbus RTU standard) • **LRC (1 byte)** All bytes are added together as unsigned 8-bit values. The 2's complement of the result will be used as a checksum. • **XOR (1 byte)** All bytes are logically XOR:ed together. The resulting byte will be used as a checksum. • **ADD (1 byte)** All bytes are added together as unsigned 16-bit values. The lowest 8 bits in the result will be used as a checksum. • **AddInvASCII (2 bytes)** All bytes are added together as unsigned 8-bit values. The lowest 8 bits in the result are inversed and used as a checksum, represented as hexadecimal ASCII (2 bytes).

9. Commands

This information is only valid for master mode and generic mode. For DF1 master mode, please refer to "Services" on page 58.

9.1 General

As mentioned previously, commands are actually predefined transactions that can be stored and reused. Just like regular transactions, commands consist of frame objects and are representations of the actual serial telegrams exchanged on the serial subnetwork.

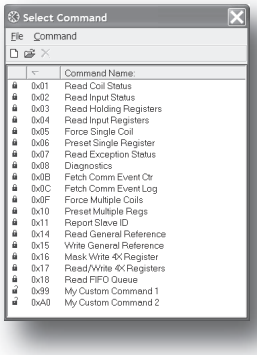
Adding a command to a node actually results in (a) transaction(s) being added according to the directions specified in the command. The frame objects in such a transaction may retrieve their values not only from parameters in the parameter section, but also from other sources such as the 'SlaveAddress'-parameter (see "Node Parameters" on page 35). In such case, the parameters in the parameter section will be greyed out and cannot be edited directly.

In Master Mode, Anybus Configuration Manager comes preloaded with commands for most common Modbus RTU functions. Additional commands can easily be added using the Command Editor (see "The Command Editor" on page 51). For DF1 Master Mode, see "Services" on page 58. In Generic Data Mode, no predefined commands exist, but custom ones may be implemented as desired.

9.2 Adding & Managing Commands

To add a command to a node, right-click on the node in the Navigation Section and select 'Add Command'.

A list of commands will appear:



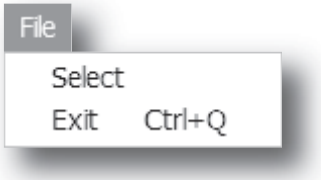
Select the desired command in the list, and select 'Add Command' in the 'Command'-menu. The specified command will be added to the node.

Just like other transactions, the frame objects of added command may be edited in the Navigation/Parameter Section or using the Transaction Editor. Note however that certain frame objects may be locked for editing.

9.2.1 Pull-Down Menu

File

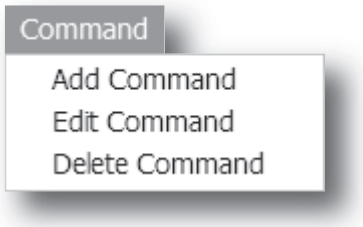
This menu features the following entries:



- **Select**
  Add the currently selected Command to the node.
- **Exit**
  Exit without adding a command to the node.

Command

This menu is used to manage the commands in the list:



- **Add Command**
  Add a custom command to the list, and open the new command in the Command Editor.
  See also "The Command Editor" on page 51.
- **Edit Command**
  Edit the currently selected command using the Command Editor.
  See also "The Command Editor" on page 51.
- **Delete Command**
  Delete the currently selected command from the list. Note that some commands are fixed and cannot be deleted.

9.2.2 Toolbar Icons

The toolbar features icons for the most commonly used functions.

- **Add Command**
  (Same as 'Add Command' in the 'Command'-menu).

- **Edit Command**
  (Same as 'Edit Command' in the 'Command'-menu).

- **Delete Command**
  (Same as 'Delete Command' in the 'Command'-menu).

9.3 The Command Editor

9.3.1 General

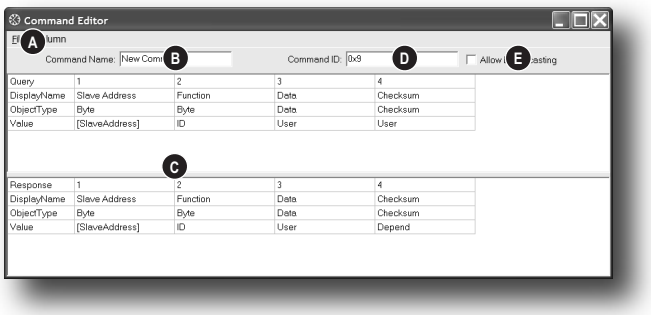
The Command Editor is used to define new commands and edit existing ones. This makes it possible to build a library of commands, which can be stored and reused at a later stage.

Note that the Command Editor is somewhat protocol-dependent in the sense that certain frame objects may not be deleted or altered.

The examples in this section use Master Mode. The procedures involved are similar in Generic Data Mode, but without the limitations imposed by the Modbus RTU protocol.

9.3.2 Basic Navigation

Open the Command Editor by selecting 'Edit Command' or 'Add Command' from the 'Command'-menu.



A: Pull-down Menu

See "Pull-down Menu" on page 52.

B: Name of Command

Actual name of the command, in text form.

C: Command Transactions

This section holds the actual transactions associated with the command. This can either be a query-response pair, or a single transaction, depending on the protocol mode etc.

D: Command ID

This can be used as desired when building the command, e.g. to specify the function code.

E: Other Settings

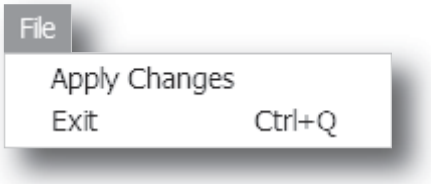
Setting	Description
Allow Broadcasting	Specifies if it is allowed to broadcast the command (only relevant in Master Mode)
Produce	The command is producing data (Generic Data Mode only)
Consume	The command is consuming data (Generic Data Mode only)

9.3.3 Pull-down Menu

File

This menu features the following entries:

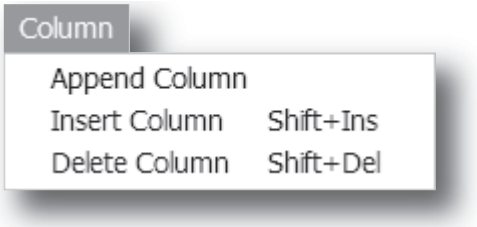
- **Apply Changes**
  Save changes and exit to the main window.
- **Exit**
  Exit without saving.



Column

The functions in this menu alters the structure of the command.

- **Append Column**
  Add another column to the command.
- **Insert Column**
  Insert a column at the selected position.
- **Delete Command**
  Delete the column at the selected position.



9.3.4 Editing a Command

As mentioned previously, the transaction section in the Command Editor represents the actual transactions associated with the command. Each column represents a frame object within the transaction.

Each column features four rows with the following parameters:

- **Query/Response/Produce/Consume**

  The upper right cell indicates the direction of the transaction.

- **DisplayName**

  Each column can be named so that the different parts of the command appears in a more user friendly manner when editing its settings in the Transaction Editor or in the Parameter Section of the Main Window.

- **ObjectType**

  This row specifies the type of frame object that shall be used for the column.

- **Value**

  This row specifies where the frame object shall retrieve its value/settings.

Value	Description
Depend	This setting is only relevant for Responses in Master Mode. The value will be retrieved from the corresponding part of the 'Query'-transaction.
Id	The value will be retrieved from the 'Command ID'-setting (see "Basic Navigation" on page 51).
User	The settings associated with the object can be edited by the user.
[SlaveAddress]	The value will be retrieved from the 'SlaveAddress'-parameter (see "Node Parameters" on page 35).
(other settings)	Other settings are no longer supported.

9.3.5 Example: Specifying a Modbus-RTU Command in Master Mode

In the following example, a Modbus-RTU command is created in Master Mode. In Modbus-RTU, a transaction always feature the following parts:

- Slave Address (1 byte)
- Function Code (1 bytes)
- A data field
- CRC (CRC-16)

Furthermore, each command always consists of a query and a response.

- **Example Query**

Query	1	2	3	4
DisplayName	Slave Address	Function	Data	Checksum
Object Type	Byte Object	Byte Object	Data Object	Checksum Object
Value	[SlaveAddress]	ID	User	User
	The value of this byte constant will be set using the 'SlaveAddress' parameter (see "Node Parameters" on page 35).	The value of this byte constant will be set using the 'Command ID'-field.	The size and location of the data associated with this object is determined by the user.	The checksum type etc can be selected by the user. By default, this is set to match the Modbus-RTU standard.

- **Example Response**

Response	1	2	3	4
DisplayName	Slave Address	Function	Data	Checksum
Object Type	Byte Object	Byte Object	Data Object	Checksum Object
Value	[SlaveAddress]	ID	User	Depend
	This value is linked to the 'SlaveAddress' parameter in the parameter window.	The value of this byte constant will be set using the 'Command ID'-field.	The size and location of the data associated with this object is determined by the user.	This object will retrieve its settings from the corresponding object in the Query.

By default, the Modbus-RTU-specific frame objects are already in place, and a data object is inserted between the function code and the CRC. These objects cannot be moved or deleted, however it is possible to add additional objects between the function code and the CRC as desired.

Name the new command by entering its name in the 'Command Name'-field, and enter a suitable function code in the 'Command ID'-field. If the command is allowed to be broadcasted, check the 'Allow Broadcasting'-checkbox.

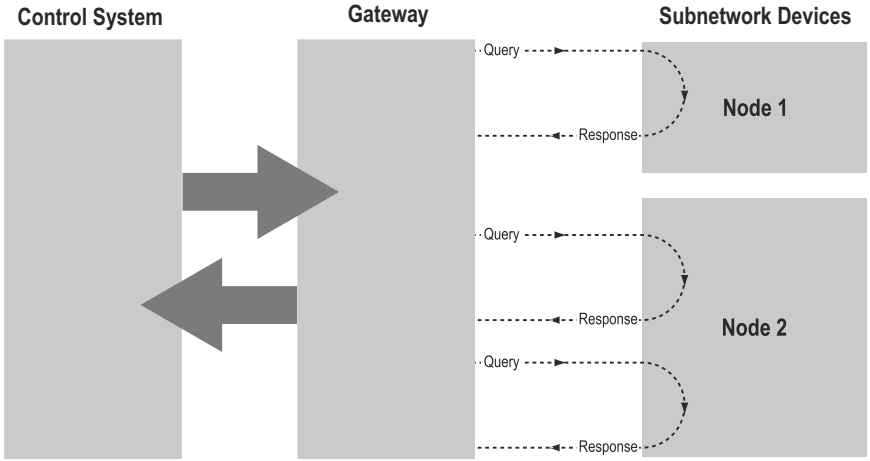
10. DF1 Protocol Mode

This mode makes it possible to let the Anybus Communicator act as a DF1 protocol master on the subnetwork.

10.1 General

In DF1 master mode, communication is based on 'services'. A 'service' represents a set of commands and operations on the subnetwork, that is predefined in the Anybus Communicator. Each service is associated with a set of parameters controlling how and when to use it on the subnetwork.

The communication is based on a query-response scheme, where the gateway issues a query on the subnetwork. The addressed node on the subnetwork is expected to issue a response to that query. Nodes are not permitted to issue responses spontaneously, i. e. without first receiving a query.



In DF1 Master Mode, Anybus Configuration Manager comes preloaded with a number of services, that can be selected by the user. The actual DF1 commands, that perform the services during runtime, are predefined in the Anybus Communicator. The configuration of the services is performed by right-clicking on a node in the Anybus Configuration Manager and selecting 'Add Command'.

10.2 ABC Parameters

(Select 'ABC' in the Navigation Section to gain access to the parameters described in this section).

Interface

Currently, only serial communication is supported.

Status / Control Word

(See "Control and Status Registers" on page 71).

Value	Description
Enabled	Enable the Control and Status Registers. The 'Data Valid'-bit in the Control Register must be set to start the subnetwork communication.
Enabled but no startup lock	This setting is similar to 'Enabled', except that the control system is not required to set the 'Data Valid'-bit to start the subnetwork communication.
Disabled	This setting completely disables the Control and Status Registers.

Module Reset

This parameter specifies how the gateway will behave in the event of a fatal error.

Value	Description
Enabled	The gateway will be restarted, and no error will be indicated to the user.
Disabled	The gateway will halt and indicate an error.

Protocol Mode

This parameter specifies which protocol mode to use for the subnetwork.

Value	Description
DF1	This mode is intended for the DF1 protocol. The Anybus Communicator can only be configured as a Master with half-duplex communication. **Note:** This is the only mode available if you intend to configure an ABC module for DF1.

See also "Protocol Modes" on page 18.

Statistics

The Transmit- and Receive Counters indicate how many transactions that have successfully been exchanged on the subnetwork. This feature is primarily intended for debugging purposes.

- **Receive Counter Location**
  Specifies the location of the Receive Counter in the internal memory buffer.
- **Transmit Counter Location**
  Specifies the location of the Transmit Counter in the internal memory buffer.

Both counters are enabled by setting 'Statistics' to 'Enabled'.

10.3 Subnetwork Parameters

(To gain access to the parameters described in this section, select 'Subnetwork' in the Navigation Section).

Communication

These parameters specify the actual communication settings used for the subnetwork.

Parameter	Description	Valid Settings
Bit rate (baud rate)	Selects the bit rate	2400 4800 9600 19200 38400 (Default)
Data bits	Selects the number of data bits	8
Parity	Selects the parity mode	None, Odd, Even
Physical standard	Selects the physical interface type	RS232, RS422, RS485
Start bits	Number of start bits.	
Stop bits	Number of stop bits.	1

DF1 Settings

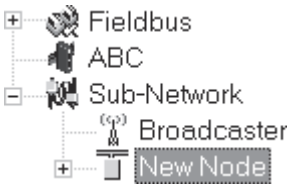
Parameter	Description
Master Node Address	Node address of the master, valid values: 0 - 254, default 1
Poll time, active slaves (10 ms)	Determines how often the slave shall be polled in steps of 10 ms, default 100 ms[a]
Poll time, inactive slaves (10 ms)	Determines how often the slave shall be polled in steps of 10 ms, default 1000 ms[b]

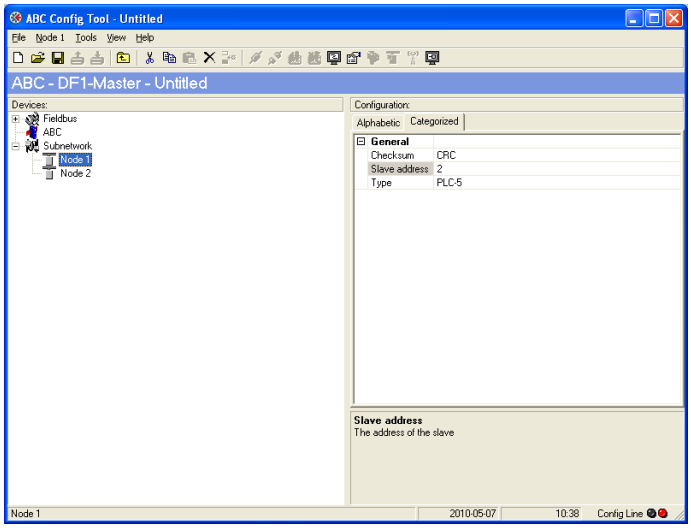
a. The default value is given as 10 in the parameter window. Each change of 10 ms either increases or decreases this value by 1, i.e. 9 represents a poll time of 90 ms and 11 represents a poll time of 110 ms.

b. The default value is given as 100 in the parameter window. Each change of 10 ms either increases or decreases this value by 1, i.e. 99 represents a poll time of 990 ms and 101 represents a poll time of 1010 ms.

10.4 Node Parameters

To gain access to the parameters described in this section, select a node in the navigation section. For more information about nodes, see "Nodes" on page 35.





Parameter	Description	Valid Settings
Checksum	Selects the type of checksum on the network.	BCC CRC (default)
Slave Address	The value entered here sets the node address.	0-254
Type	The PLC type of the slave	PLC-5 SLC500 MicroLogix

10.5 Services

Services are commands that can be stored and reused. The user configures each slave with services that can be issued from the master. A total of 50 services are allowed.

The Anybus Communicator supports a selection of DF1 commands. When the gateway is going to execute a service, it automatically chooses the appropriate DF1 command(s) that are used to perform the service on the selected DF1 node type.

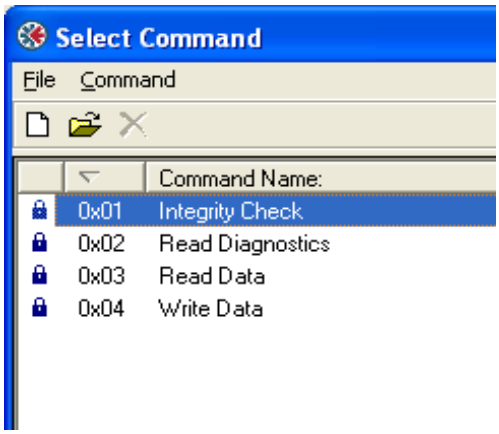
10.5.1 Available Services

Right click on the node, and choose Add Command. A pop-up window will show the four different services that are available:

- Integrity check
- Read diagnostics
- Read data
- Write data

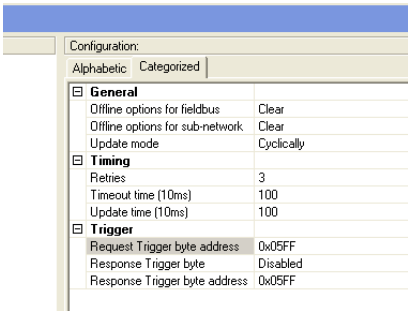
A maximum of 50 services in total (for all nodes) can be selected.

The predefined services can be configured to suit the application. Select a service to show the parameters.



General Configuration Parameters

These parameters are common to all services, but the settings are individual to each instance of a service.



General:

Parameter	Description	Valid settings
Offline options for fieldbus	The action to take for this service if the fieldbus goes offline. This option affects the data that is sent out to the subnetwork.	Clear Freeze Noscanning
Offline options for subnetwork	The action to take for this service if the subnetwork goes offline. This option affects the data that is reported to the fieldbus master.	Clear Freeze
Update mode	The update mode for this service	Cyclically On data change Single shot Change of state on trigger

Timing:

Parameter	Description	Default
Retries	The number of times to resend this service before the node is disconnected	3
Timeout time (10 ms)	The time to wait before resending this service (in steps of 10 ms)[a]	1000 ms
Update time (10 ms)	The minimum time between two services of this kind (in steps of 10 ms)[a]	1000 ms

a. The default value is given as 100 in the parameter window. Each change of 10 ms either increases or decreases this value by 1, i.e. 99 represents a poll time of 990 ms and 101 represents a poll time of 1010 ms.

Trigger:

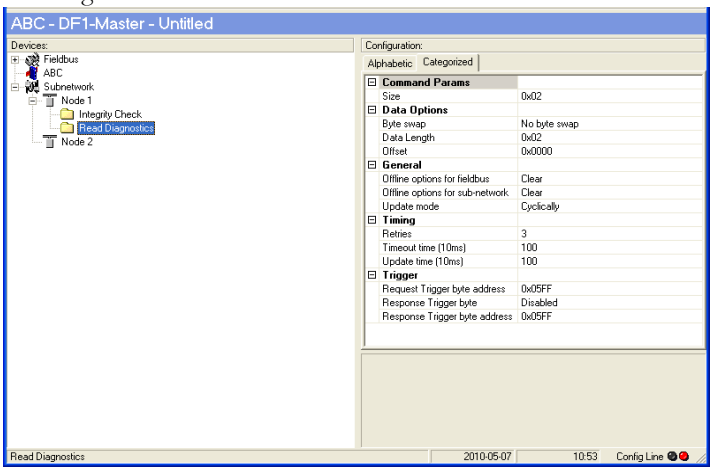
Parameter	Description	Default
Request Trigger byte address	The memory location of the trigger byte this service uses for updates on trigger byte changes	0x05FF
Response Trigger byte	Enables/disables the trigger byte	Disabled
Response Trigger byte address	The memory location of the trigger byte this service uses for updates on trigger byte changes Valid settings range from 0x200... 0x3FF and 0x400... 0xNNN	0x05FF

10.6 Integrity Check

This service checks that a node is up and running correctly. A telegram is sent to the node. The node mirrors and returns the telegram. No configuration is needed, apart from the general parameters, common to all services.

10.7 Read Diagnostics

This service reads diagnostic information from the module.



Command parameters

The command parameter Size decides the amount of data that can be read. The size is given in bytes which means that it always has to be an even number as only whole elements can be read from the slave. One bit/integer element is 2 bytes and one float element is 4 bytes. The range of the size differs, depending on node type:

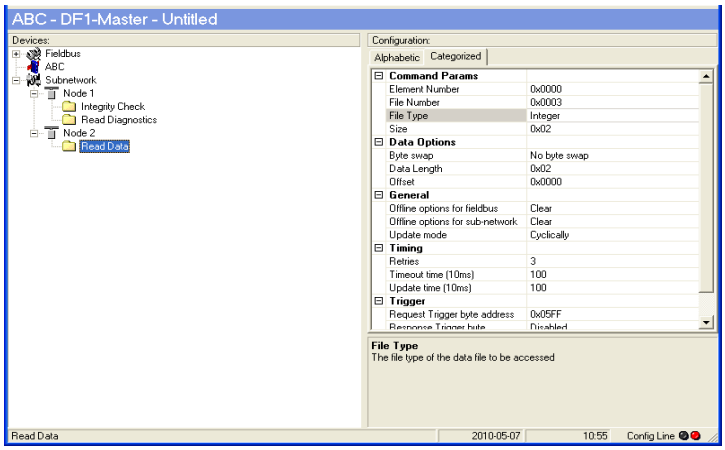
	PLC-5	SLC500	MicroLogix
Size range (in bytes)	1-26	1-28	1-26

Data options:

Parameter	Description	Valid settings
Byte swap	Determines if the data shall be swapped	No byte swap Swap words Swap double words
Data length	The number of bytes, read from the DF1 network, to write to the area determined by the Offset parameter	≤ Size
Offset	The offset in the internal memory buffer in the module, where the data shall be read. See “Memory Map” on page 16	

10.8 Read Data

This service is used to read data from the nodes in the subnetwork.



Command Parameters

Parameter	Description	Valid settings
Element Number	The element number of the data file to be accessed within the slave.	PLC-5: 0-999 SLC500: 0-255 MicroLogix: 0-255
File number	The file number of the data file to be accessed.	PLC-5: 3, 7, 8, 10-999 SLC500: 3, 7, 8, 10-255 MicroLogix: 3, 7, 8, 10-255
File type	The file type of the data to be accessed.	Integer Bit Float
Size	The number of bytes to read from the slave. One bit/integer element is 2 bytes and one float element is 4 bytes. The parameter must have an even value as only whole elements can be read from the slave.	PLC-5: 2-240 SLC500: 2-236 MicroLogix: 2-242

Data Options

Parameter	Description	Valid settings
Byte swap	Determines if the data shall be swapped.	No byte swap Swap words Swap double words
Data length	The number of bytes, read from the DF1 network, to write to the area determined by the Offset parameter	≤ Size
Offset	The offset in the internal memory buffer in the module, where the data shall be read. See “Memory Map” on page 16. **Note**: If the control and status registers are enabled (default), first available data location will be: Input area 0x002, Output area 0x202.	-

10.9 Write Data

This service is used to write data to the nodes in the subnetwork. The parameters to be configured are the same as for the service Read Data. The only difference is that data is read from the internal memory buffer in the Anybus Communicator and written to the subnetwork bus, instead of being written to the internal memory buffer.

11. Subnetwork Monitor

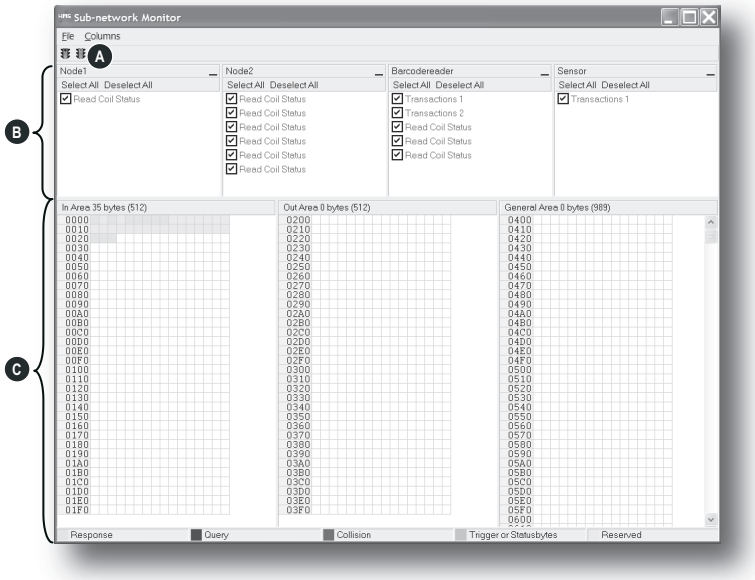
General

The Subnetwork Monitor is intended to simplify configuration and troubleshooting of the subnetwork. Its main function is to display the data allocated for subnetwork communication and detect if any area has been allocated twice (i.e if a collision has occurred).

All configured nodes, and their transactions, are listed in the middle of the screen (B). Selecting and de-selecting single transactions makes it possible to view any combination of allocated data.

Note: The subnetwork monitor has a negative influence on the overall performance of the gateway. Therefore the monitor functionality should be used with care.

Operation



A: Start Network & Stop Network Icons

These icons controls the subnetwork activity. To stop all subnetwork activity, click on the red light. To start the subnetwork again, click on the green light.

Start

Stop

B: Nodes / Transactions

To view data blocks associated with a transaction, select the transaction in the list. The corresponding data will then appear in the Monitor Section (C).

C: Monitor Section

This section visualizes how data is allocated in the Input, Output and General Data areas.

Color	Meaning
White	Not allocated.
Yellow	Data allocated by a Response or Consume transaction.
Blue	Data allocated by a Query or Produce transaction
Red	Collision; area has been allocated more than once.
Grey	Reserved (illustrates memory consumption, area can be allocated if necessary)
Green	Data allocated by Trigger byte, Transmit/Receive Counter, or Control/Status Registers.

12. Node Monitor

12.1 General

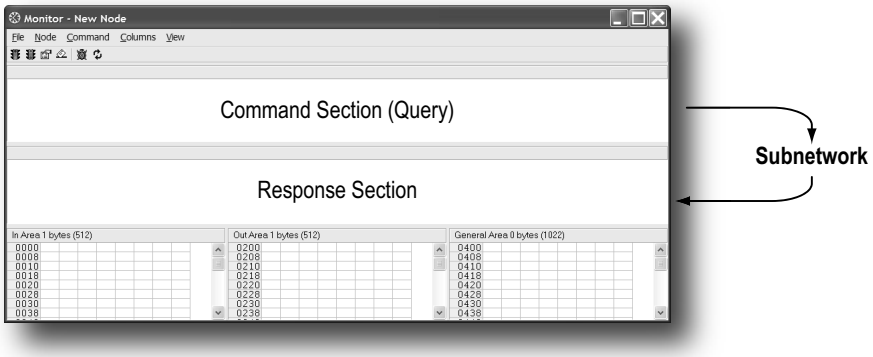
The Node Monitor can provide valuable information when setting up the communication with the subnetwork, by allowing individual commands to be issued manually, and monitoring the response (if applicable). It also provides an overview of the memory used by a particular node.

Note: The node monitor has a negative influence on the overall performance of the gateway, i.e. it should be used only when necessary.

The Node Monitor behaves somewhat differently in the three protocol modes:

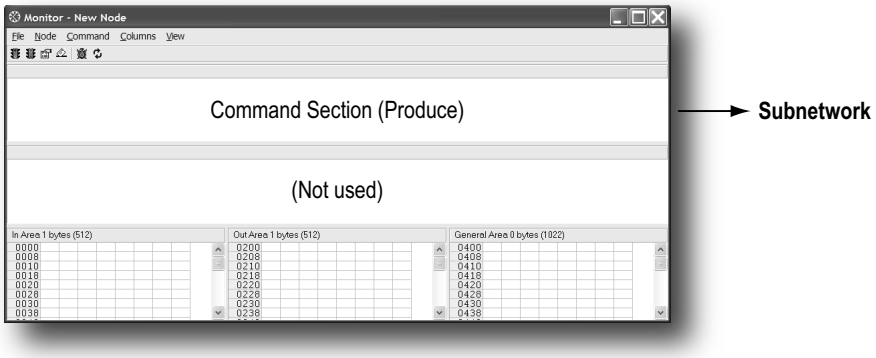
- **Master Mode and DF1 Master Mode**

  The selected Command (Query Transaction) or Service is sent to the subnetwork. The response to the Query can be monitored in the Response Section.

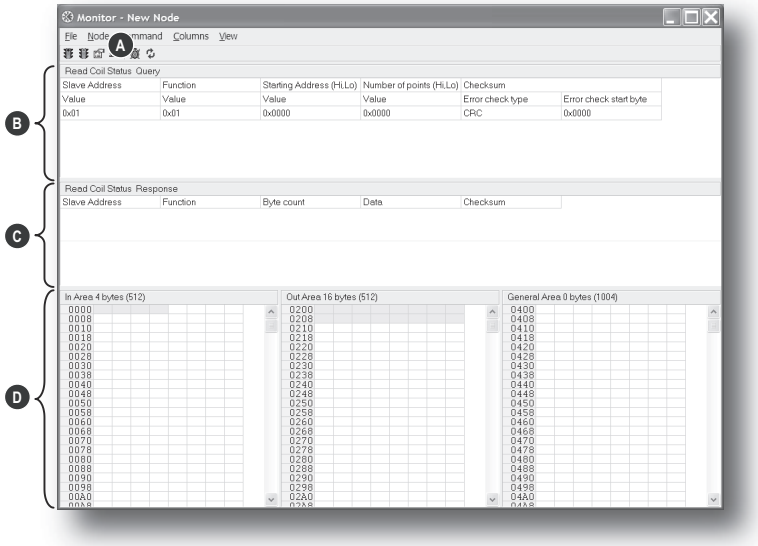


- **Generic Data Mode**

  The selected command (Transaction Produce) is sent to the subnetwork. It is not possible to monitor any responses etc. generated by other nodes.



12.2 Navigating the Node Monitor



A: Pull-down Menu & Toolbar Icons

See "Pull-Down Menu" on page 65 and "Toolbar Icons" on page 66.

B: Command Section

This section holds the currently selected command. The individual frame objects in the command can be edited in a similar way as in the Transaction and Command Editors.

C: Response Section (Master Mode and DF1 Master Mode only)

This section holds the response to the selected Command.

D: Monitor Section

This section displays the data associated with the node. Areas in dark grey are reserved for the Status & Control Registers, and areas displayed in light grey represent the data that is used by the node.

The data displayed in this section will be refreshed based on the refresh-icons in the toolbar. For more information, see "Toolbar Icons" on page 66.

12.2.1 Pull-Down Menu

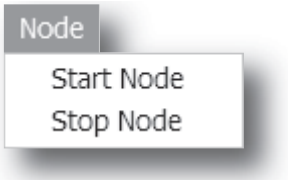
File

There is only one entry in this menu:

- **Exit**
  This will close the Node Monitor. Note however that if the node has been disabled using 'Stop Node' (see below), it will not resume data exchange until enabled again using 'Start node'.

Node

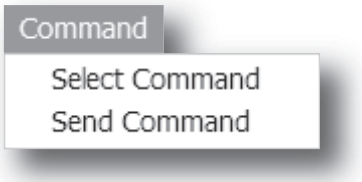
This menu controls the data exchange for the node. This feature can help isolate problems associated with a particular node.



- **Start Node**
  Enable the transactions associated with the node.
- **Stop Node**
  Disable the transactions associated with the node.

Command

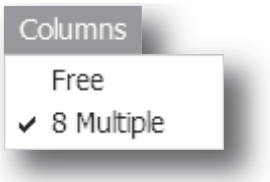
This menu is used to specify and issue a command manually.



- **Select Command**
  Select a command to be sent to the subnetwork.
- **Send Command**
  Send the specified command to the subnetwork.

Columns

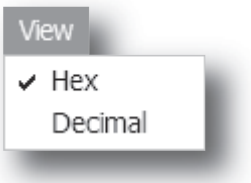
This menu specifies the number of columns in the Monitor Section.



- **Free**
  The number of columns depends on the width of the window.
- **8 Multiple**
  The number of columns will be fixed to 8.

View

This menu specifies the data representation in the Monitor Section.



- **Hex**
  Display the data in hexadecimal format.
- **Decimal**
  Display the data in decimal format.

12.2.2 Toolbar Icons

The toolbar features icons for the most commonly used functions.

- **Start Node & Stop Node**

  These icons corresponds to the functions in the 'Node'-menu.

  See also "Node" on page 65.

- **Select Command & Send Command**

  These icons corresponds to the functions in the 'Command'-menu.

  See also "Command" on page 65.

- **Resume Refresh & Stop Refresh**

  When enabled, the data displayed in the Monitor Section will be refreshed cyclically. When disabled, i.e. stopped, the data will have to be refreshed manually using the 'Refresh'-icon (see below).

- **Refresh**

  When clicking on this icon, the data displayed in the Monitor Section will be refreshed.

13. Data Logger

13.1 General

This feature allows the subnetwork traffic to be logged into a buffer for examination. This may provide valuable information when debugging the lowest levels of the subnetwork communication.

Note that the logger function is part of the gateway itself and is separate from the Anybus Configuration Manager. This means that logging can be performed even if the gateway is physically disconnected from the PC running the Anybus Configuration Manager.

13.2 Operation

Start & Stop Logging

- **Start logging**

  Select 'Start Logging' in the 'Tools'-menu. Anybus Configuration Manager will then prompt for the desired mode of operation, see below.

- **Stop logging**

  Select 'Stop Logging' in the 'Tools'-menu. This will open the log-window, see below.

Modes of Operation

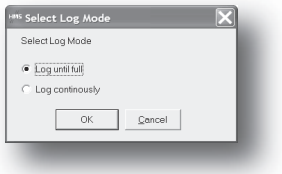
Select the desired mode of operation and click 'OK' to start logging data.

- **Log until full**

  Data will be logged until the log-buffer is full.

- **Log continuously**

  Data will be logged continuously until logging is stopped by clicking 'Stop Logging'. The log-buffer will contain the most recent data.

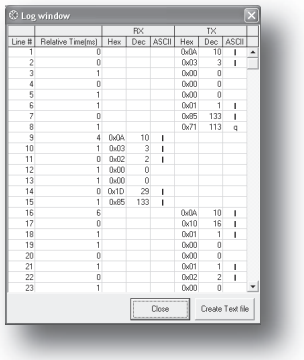


Log Window

The logged data is displayed in hexadecimal, decimal and ASCII format for both directions. The time between the log-entries is displayed in a separate column.

The data may optionally be saved in ASCII text format by clicking 'Create Text file'.

Click 'Close' to exit.



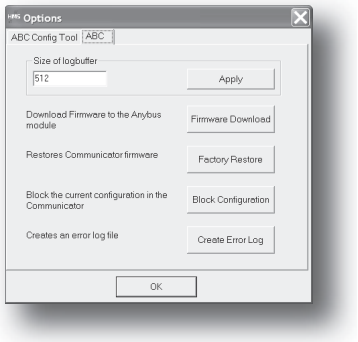
13.3 Configuration

By default, the log-buffer can hold 512 bytes of data in each direction. To specify a different size for the buffer, select 'Options' in the 'Tools'-menu.

A window with various settings will appear. Select the 'ABC'-tab, and enter the desired number of buffer entries under 'Size of logbuffer' (valid settings range from 1...512).

Click 'Apply' to validate the new settings.

Click 'OK' to exit.



14. Configuration Wizards

14.1 General

When creating a new subnetwork configuration, the Anybus Configuration Manager provides a choice between starting out with a blank configuration, or using a predefined template, a.k.a a wizard.

The wizard automatically creates a subnetwork configuration based on information supplied by the user, i.e the user simply has to "fill in the blanks". Note however that this will only work when the subnetwork fits the wizard profile; in all other cases the 'Blank Configuration' option must be used.

14.2 Selecting a Wizard Profile

The following window appears each time the Anybus Configuration Manager is started, or upon selecting the 'New' entry in the 'File'-menu (unless it has been disabled in the 'Options'-menu, see "Tools" on page 28).

Currently, the following wizards are available:

- **ABCC ExtLink Wizard**

  This wizard is intended for use with the Anybus-CompactCom Modbus-RTU fieldbus communication adapter.

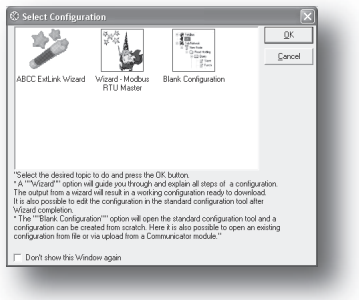
- **Wizard - Modbus RTU Master**

  This option is suitable for Modbus RTU-based networks.

  See also "Wizard - Modbus RTU Master" on page 70.

- **Blank Configuration**

  This option creates an empty configuration.


Select Configuration
OK
Cancel
ABCC ExtLink Wizard
Wizard - Modbus RTU Master
Blank Configuration
"Select the desired topic to do and press the OK button.
* A ""Wizard"" option will guide you through and explain all steps of a configuration. The output from a wizard will result in a working configuration ready to download. It is also possible to edit the configuration in the standard configuration tool after Wizard completion.
* The ""Blank Configuration"" option will open the standard configuration tool and a configuration can be created from scratch. Here it is also possible to open an existing configuration from file or via upload from a Communicator module."
Don't show this Window again

Highlight the desired wizard and click 'OK' to continue.

14.3 Wizard - Modbus RTU Master

This wizard can be used to create a Modbus-RTU-based network configuration based on certain information about the subnetwork. The online help system explains each configuration step in detail.

- **Important Notes:**

  Many OEM devices do not fully comply with the Modbus standard. For example, they may implement a variation of this standard or be limited to the use of specific Modbus commands other than the ones used by this wizard. In all cases, the user should consult the documentation of the devices that shall be used on the subnetwork for information about their serial communication requirements, and if necessary contact the manufacturer of the device to obtain further information about the serial communication protocol.

  In the event that the wizard doesn't handle a particular Modbus command required by a device, it is possible to specify this command manually as a transaction in the Anybus Configuration Manager.

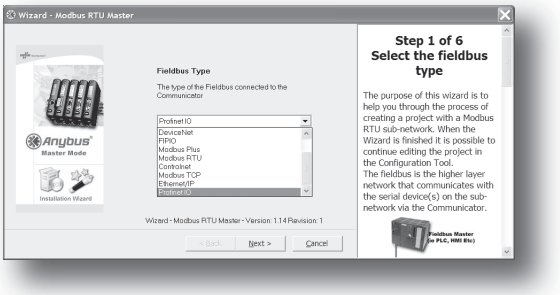
Using this wizard involves the following steps:

Step 1: Communicator Type

Select 'EtherCAT'.

Click 'Next' to continue.

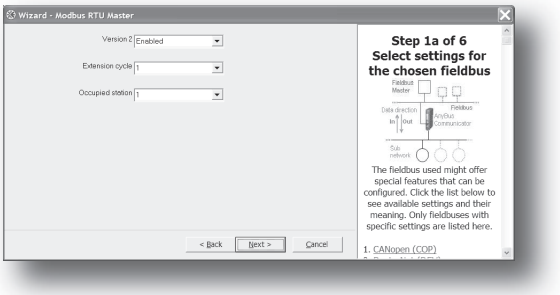
Tip: It is possible to return to a previous menu at any time without losing any settings by clicking 'Previous'.


Wizard - Modbus RTU Master
Fieldbus Type
The type of the Fieldbus connected to the Communicator
Profinet IO
DeviceNet
PIPO
Modbus Plus
Modbus RTU
ControlNet
Modbus TCP
Ethernet/IP
Profinet IO
Anybus
Master Mode
Installation Wizard
Wizard - Modbus RTU Master - Version: 1.14 Revision: 1
< Back
Next >
Cancel
Step 1 of 6
Select the fieldbus type
The purpose of this wizard is to help you through the process of creating a project with a Modbus RTU sub-network. When the Wizard is finished it is possible to continue editing the project in the Configuration Tool.
The fieldbus is the higher layer network that communicates with the serial device(s) on the sub-network via the Communicator.

Step 1a: I/O Sizes

Specify the sizes of the input and output data areas. For more information, see "IO Sizes" on page 31.

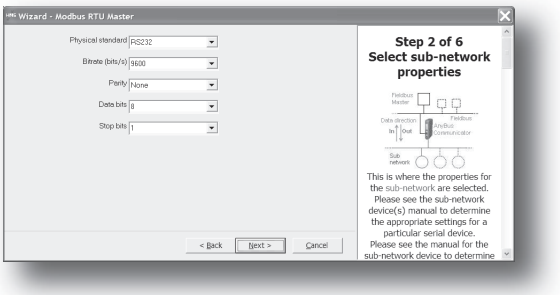
Click 'Next' to continue.


Wizard - Modbus RTU Master
Version 2 Enabled
Extension cycle 1
Occupied station 1
< Back
Next >
Cancel
Step 1a of 6
Select settings for the chosen fieldbus
The fieldbus used might offer special features that can be configured. Click the list below to see available settings and their meaning. Only fieldbuses with specific settings are listed here.
1. CANopen (COP)

Step 2: Physical Settings

Select the physical properties of the subnetwork.

Click 'Next' to continue.


Wizard - Modbus RTU Master
Physical standard RS232
Bitrate (bits/s) 9600
Parity None
Data bits 8
Stop bits 1
< Back
Next >
Cancel
Step 2 of 6
Select sub-network properties
This is where the properties for the sub-network are selected. Please see the sub-network device(s) manual to determine the appropriate settings for a particular serial device.
Please see the manual for the sub-network device to determine

Steps 3 - 6

Consult the online help system for further information.

15. Control and Status Registers

15.1 General

The Control and Status Registers are disabled by default, but can be enabled using the Anybus Configuration Manager (see "Status / Control Word" on page 32). These registers form an interface for exchanging status information between the subnetwork and the fieldbus control system.

The main purpose of these registers is to...

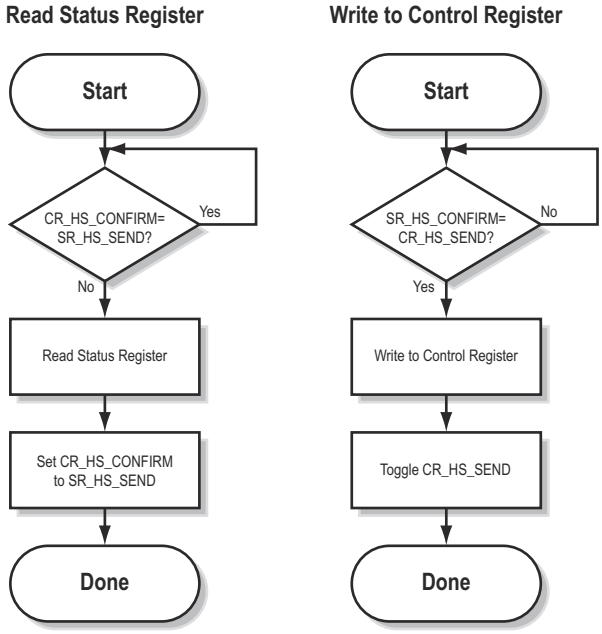
- Report subnetwork related problems to the fieldbus control system
- Ensure that only valid data is exchanged in both directions
- Enable the fieldbus control system to start/stop data exchange with selected nodes on the subnetwork

If enabled, these registers occupy the first two bytes in the input and output data areas (0x000-0x001 and 0x200-0x201 respectively), which means they can be accessed from the fieldbus just like any other data in these areas.

Note: Internally, these registers are stored in Motorola-format (i.e. MSB first). If the higher level network uses a different byte order, the upper and lower bytes will appear swapped.

15.1.1 Handshaking Procedure

A special handshaking procedure, which is illustrated in the two flowcharts below, must be followed when accessing these registers to ensure that both parts receive proper information.



15.1.2 Data Consistency

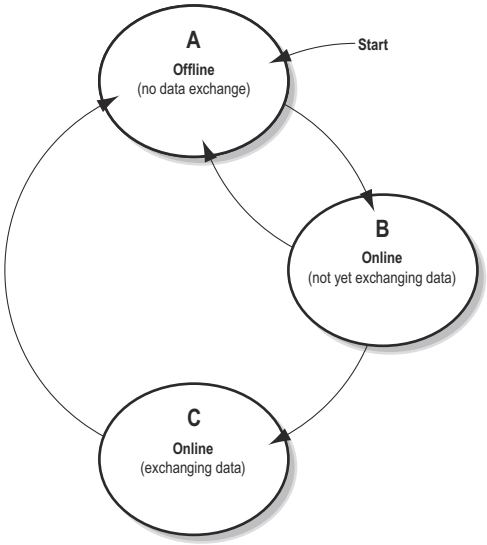
The 'Data Valid'-bits in the Control and Status Registers are used to ensure data consistency during start-up and fieldbus offline/online transitions.

If the 'Status / Control Word'-parameter in Anybus Configuration Manager is set to 'Enabled', the gateway will wait for the fieldbus control system to set the 'Data Valid'-bit in the Control Register before it starts exchanging data on the subnetwork.

If the same parameter is set to 'Disabled' or 'Enabled but no startup lock', communication will start as soon as the fieldbus goes online.

State Machine

The fieldbus network participation can be described using a state machine as described below.



A: Offline (No data exchange)

1. Clear the 'Data Valid'-bit in the Control Register.
2. Write initial data to the Output Area according to the subnetwork configuration.
3. Wait until the fieldbus control system and the gateway are online on the fieldbus network, and shift to state B.

B: Online (Not yet exchanging data)

4. Wait until the 'Data Valid'-bit in the Status Register is cleared by the gateway.
5. Set the 'Data Valid'-bit in the Control Register.
6. When the 'Data Valid'-bit in the Status Register is set by the gateway, shift to state C.
7. If the gateway goes offline on the fieldbus, shift to state A.

C: Online (Exchanging data)

Exchanging valid data in both directions.
If the gateway goes offline on the fieldbus, shift to state A.

Note: The gateway cannot spontaneously clear the 'Data Valid'-bit in the Status Register.

Latency

The 'Data Valid'-bit in the Status Register may in some cases be delayed. This latency can be caused by a missing node or a bad connection to a node with a long timeout value assigned to it.

Therefore, the fieldbus control system should not wait for this bit to be set before communicating with the subnetwork devices; it should be considered as an aid for the fieldbus control system to know when all data has been updated.

15.2 Status Register Contents (Gateway to Control System)

15.2.1 General Information

The Status Register is (if enabled) located at 0x000-0x001 and constitutes a bit-field as follows:

bit(s)	Name	Description
15	Send (SR_HS_SEND)	These bits control the handshaking towards the fieldbus control system. See also... - "Handshaking Procedure" on page 71 - "Control Register Contents (Control System to Gateway)" on page 75
14	Confirm (SR_HS_CONFIRM)	
13	Data Valid (Master Mode and DF1 Master Mode Only)	This bit is set when all transactions have been executed successfully at least once. Once set, it will not change. 1:Data Valid 0:Data not Valid **Note:** This bit is not used in Generic Data Mode.
12... 8	Status Code	This field holds the last status report from the gateway. See also... - "Status Codes in Master Mode and DF1 Master Mode" on page 73 - "Status Code in Generic Data Mode" on page 74
7... 0	Data	

Note: Internally, this is treated as a Motorola-format word (i.e. MSB first). If the higher level network uses a different byte order, the upper and lower bytes will appear swapped.

15.2.2 Status Codes in Master Mode and DF1 Master Mode

(This table is valid only in Master Mode and DF1 Master Mode).

Code	Condition	Type	Data	Description
0x00	Retransmission Counter Updated	Warning	Counter	The number of retransmissions on the subnetwork has increased. If this problem persists, this may eventually trigger a Single- or Multiple Node(s) Missing condition.
0x01	Single Node Missing	Error	Slave address	A single node is missing.
0x02	Multiple Nodes Missing	Error	Number of nodes	Multiple nodes are missing.
0x03	Buffer Overrun	Warning	Slave address	A node returned more data than expected.
0x04	Other Error	Error	Slave address	Undefined error
0x1F	No Error	Warning	-	No errors

Note: Conditions of type 'Error' will eventually be followed by a 'No Error' condition when the cause has been resolved. Conditions of type 'Warning' are however considered informational and may not necessarily be followed by a 'No Error' condition later on.

15.2.3 Status Code in Generic Data Mode

(This table is valid only in Generic Data Mode).

Code	Condition	Type	Data	Description
0x00	Invalid Transaction Counter Updated	Error	Counter	The number of invalid transactions (i.e. received transactions which doesn't match any of the consume-transactions defined in the subnetwork configuration) has increased.
0x01	Frame Error	Warning	-	End character is enabled, but a message delimiter timeout occurs prior to receiving it.
0x02	Offline Timeout Counter Updated	Error	Counter	The of number of timed out consume-transactions has increased. See also... - "Consume-Transactions" on page 41 (Offline timeout time)
0x03	Buffer Overrun	Warning	-	A node returned more data than expected - or - the gateway was unable to finish processing a message prior to receiving a new one.
0x04	Other Error	Error	-	Undefined error
0x1F	No Error	Warning	-	No errors

Note: Conditions of type 'Error' will eventually be followed by a 'No Error' condition when the cause no longer is detected. Conditions of type 'Warning' are however considered informational and may not necessarily be followed by a 'No Error' condition later on.

15.3 Control Register Contents (Control System to Gateway)

15.3.1 General Information

The Control Register is (if enabled) located at 0x200-0x201 and constitutes a bit-field as follows:

bit(s)	Name	Description
15	Confirm (CR_HS_CONFIRM)	These bits control the handshaking towards the gateway. See also... - "Handshaking Procedure" on page 71 - "Status Register Contents (Gateway to Control System)" on page 73
14	Send (CR_HS_SEND)	
13	Data Valid	This bit controls data consistency (see "Data Consistency" on page 72). 1:Output Area valid; exchange data on the subnetwork 0:Output Area not valid; do not exchange data on the subnetwork **Note:** This bit is only relevant if the Control/Status Registers are set as 'Enabled'
12	Execute Command	If set, the specified command will be executed by the gateway (see below).
11... 8	Control Code	This field holds commands which can be executed by the gateway (see below). See also... - "Control Codes in Master Mode and DF1 Master Mode" on page 75 - "Control Codes in Generic Data Mode" on page 75
7... 0	Data	

Note: Internally, this is treated as a Motorola-format word (i.e. MSB first). If the higher level network uses a different byte order, the upper and lower bytes will appear to be swapped.

15.3.2 Control Codes in Master Mode and DF1 Master Mode

(This table is valid only in Master Mode and DF1 Master Mode).

Code	Instruction	Data	Description
0x00	Disable Node	Actual node address	Disables the specified node.
0x01	Enable Node	Actual node address	Enables a previously disabled node.
0x02	Enable Nodes	Actual number of nodes to enable	Enables the specified number of nodes, starting from the first node in the configuration. Remaining nodes will be disabled.

15.3.3 Control Codes in Generic Data Mode

(No Control Codes are currently supported in this mode).

16. Advanced Fieldbus Configuration

16.1 General

The fieldbus interface of the gateway consists of an embedded Anybus-S communication interface. Normally, the Anybus-S configuration settings are set up automatically by the gateway. However, advanced users can configure the Anybus-S card for specific features. This chapter assumes that the reader is familiar with the Anybus-S and it's application interface. For more information about the Anybus-S platform, consult the Anybus-S Parallel Design Guide.

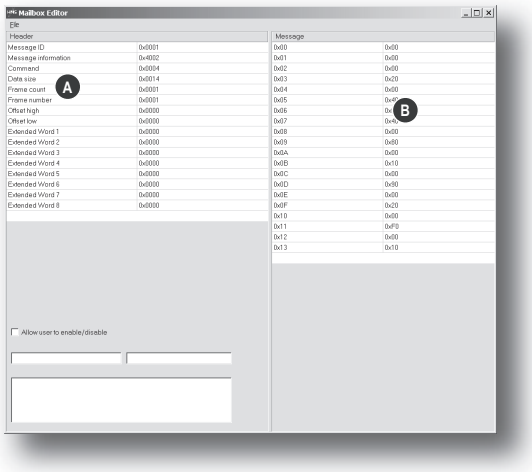
The standard initialization parameters are determined by the subnetwork configuration. Information about the amount of input and output data used for subnetwork communication is used by Anybus Configuration Manager to create the configuration message that sets the sizes of the input and output data areas in the Dual Port RAM of the embedded Anybus-S interface. It is possible to add fieldbus specific mailbox messages to customize the initialization. This is done in the Mailbox Editor, see below.

(A mailbox message is a HMS specific command structure used for low-level communication with an Anybus-S interface. Consult the Anybus-S Parallel Design Guide and the fieldbus appendix for the desired fieldbus for further information.)

16.2 Mailbox Editor

To add a mailbox message to the configuration, right-click on 'EndInit' and select 'Insert New Mailbox'.

A mailbox message consists of a Header section and a data section where the Header consists of 16 words (32 bytes) and the data section consists of up to 128 words (256 bytes). All fields are editable except the Message information field that is fixed to 0x4002, which means that only fieldbus specific mailbox messages can be entered here.



The mailbox message is presented as two columns; one contains header information (A), the other one contains the message data (B).

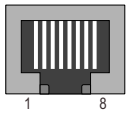
To add message data, simply change the Data size parameter in the header column (A), and the corresponding number of bytes will appear in the message data column (B).

For more information about fieldbus specific mailbox messages, consult the separate Anybus-S Fieldbus Appendix for the fieldbus you are using. For general information about the Anybus-S platform, consult the Anybus-S Design Guide.

A. Connector Pin Assignments

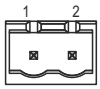
A.1 EtherCAT Connectors

Pin	Signal
Housing	Cable Shield
1	TD+
2	TD-
3	RD+
4	Termination
5	Termination
6	RD-
7	Termination
8	Termination



A.2 Power Connector

Pin	Description
1	+24V DC
2	GND

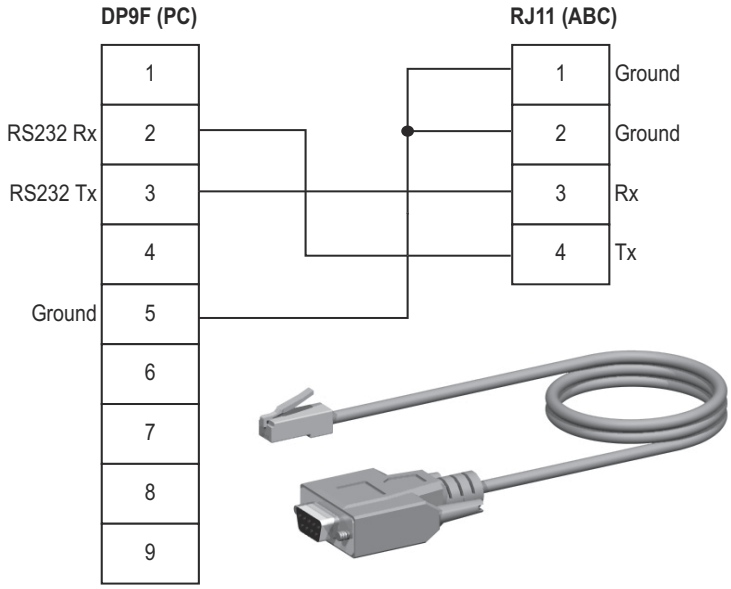


Notes:

- Use 60/75 or 75×C copper (CU) wire only.
- The terminal tightening torque must be between 5... 7 lbs-in (0.5... 0.8 Nm)

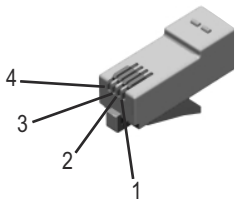
A.3 PC Connector

Configuration Cable Wiring



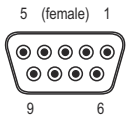
RJ11 (4P4C modular)[1] : ABC

Pin	Description
1	Signal ground
2	
3	RS232 Rx (Input)
4	RS232 Tx (Output)



DB9F : PC

Pin	Description
1	-
2	RS232 Rx (Input)
3	RS232 Tx (Output)
4	-
5	Signal Ground
6 - 9	-



1. The RJ11 (4P4C modular) is sometimes referred to as an RJ9.

A.4 Subnetwork Interface

A.4.1 General Information

The subnetwork interface provides for RS232, RS422 and RS485 communications. Depending on the configuration specified in the Anybus Configuration Manager, different signals are activated in the subnetwork connector.

A.4.2 Bias Resistors (RS485 Only)

When idle, RS485 enters an indeterminate state, which may cause the serial receivers to pick up noise from the serial lines and interpret this as data. To prevent this, the serial lines should be forced into a known state using pull-up and pull-down resistors, commonly known as bias resistors.

The bias resistors form a voltage divider, forcing the voltage between the differential pair to be higher than the threshold for the serial receivers, typically >200mV.

Note that bias resistors shall only be installed on one node; installing bias resistors on several nodes may compromise the signal quality on the network and cause transmission problems.

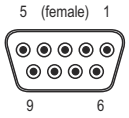
A.4.3 Termination (RS485 & RS422 Only)

To avoid reflections on the serial lines, it is important to properly terminate the subnetwork by placing termination resistors between the serial receivers near the end nodes.

The resistor value should ideally match the characteristic impedance of the cable, typically 100... 120R.

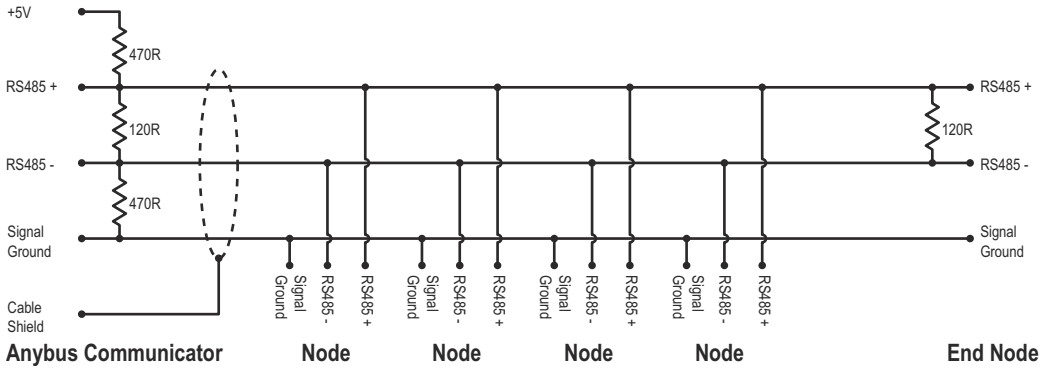
A.4.4 Connector Pinout (DB9F)

Pin	Description	RS232	RS422	RS485
1	+5V Output(100mA max)	✓	✓	✓
2	RS232 Rx	✓		
3	RS232 Tx	✓		
4	(reserved)			
5	Signal Ground[a]	✓	✓	✓
6	RS422 Rx +		✓	
7	RS422 Rx -		✓	
8	RS485 + /RS422 Tx+		✓	✓
9	RS485 - /RS422 Tx-		✓	✓
(housing)	Cable Shield	✓	✓	✓

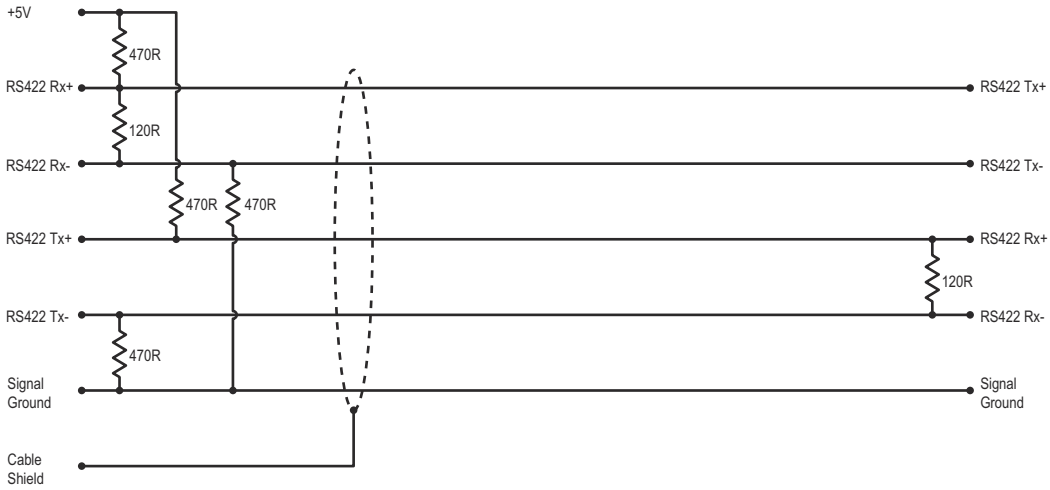


a. Connecting this signal directly to Protective Earth (PE) of other nodes may, in case of grounding loops etc., cause damage to the on-board serial transceivers. It is therefore generally recommended to connect it only to Signal Ground (if available) of other nodes.

A.4.5 Typical Connection (RS485)

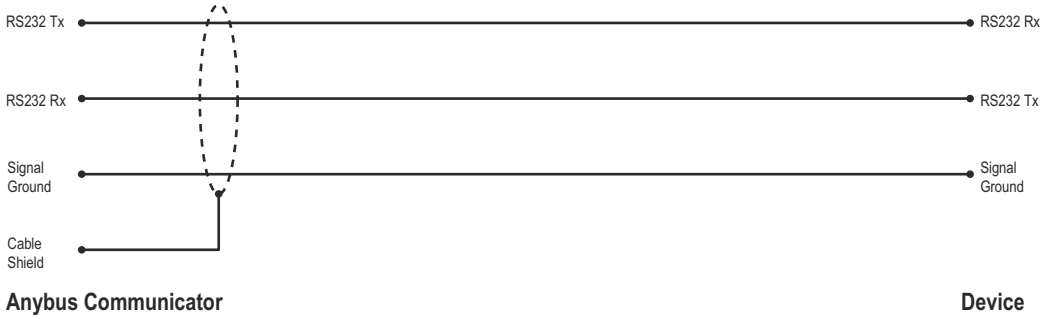


A.4.6 Typical Connection (RS422 & 4-Wire RS485)



Note: Bias resistors are normally not needed on RS422, but may be required when using 4-wire RS485.

A.4.7 Typical Connection (RS232)



B. Technical Specification

B.1 Mechanical Properties

Housing

Plastic housing with snap-on connection to DIN-rail, protection class IP20

Dimensions

120 mm x 75 mm x 27 mm, L x W x H (inches: 4.72” x 2.95” x 1.06”; L x W x H)

B.2 Electrical Characteristics

Power Supply

Power: 24V ± 10%

Power Consumption

Maximum power consumption is 280mA on 24V. Typically around 100mA

B.3 Environmental Characteristics

Relative Humidity

The product is designed for a relative humidity of 0 to 95% non-condensing

Temperature

Operating:	±0°C to +55°C
Non Operating:	-25°C to +85°C

B.4 Regulatory Compliance

EMC Compliance (CE)

This product is in accordance with the EMC directive 89/336/EEC, with amendments 92/31/EEC and 93/68/EEC through conformance with the following standards:

- **EN 50082-2 (1993)**

  EN 55011 (1990)Class A

- **EN 61000-6-2 (1999)**

  EN 61000-4-3 (1996)10V/m

  EN 61000-4-6 (1996)10V/m(all ports)

  EN 61000-4-2 (1995)±8kVAir Discharge
  ±4kVContact discharge

  EN 61000-4-4 (1995)±2kVPower port
  ±1kVOther ports

  EN 61000-4-5 (1995)±0.5kVPower ports (DM/CM)
  ±1kVSignal ports

UL/c-UL compliance

The certification has been documented by UL in file E214107.

Galvanic isolation on subnetwork interface

- **EN 60950-1 (2001)**

  Pollution Degree 2

  Material Group IIIb

  250 V_{RMS} or 250 VDCWorking voltage

  500 VSecondary circuit transient rating

C. Troubleshooting

Problem	Solution
Problem during configuration Upload / Download. The Config Line “LED” turns red in the Anybus Configuration Manager.	• Serial communication failed. Try again
The serial port seems to be available, but it is not possible to connect to the gateway	• The serial port may be in use by another application. Exit the Anybus Configuration Manager and close all other applications including the ones in the system tray. Try again • Select another serial port Try again
Poor performance	• Right click ‘subnetwork’ in the Navigation window and select ‘subnetwork Status’ to see status / diagnostic information about the subnetwork. If the gateway reports very many retransmissions, check your cabling and/or try a lower baud rate setting for the subnetwork (if possible). • Is the Subnet Monitor in the Anybus Configuration Manager active? The subnetwork monitor has a negative influence on the overall performance of the gateway, and should only be used when necessary. • Is the Node Monitor in the Anybus Configuration Manager active? The node monitor has a negative influence on the overall performance of the gateway, and should only be used when necessary.
No subnetwork functionality	• Use the ‘Data logger’-functionality to record the serial data communication on the subnetwork. • If no data is being transmitted, check the configuration in Anybus Configuration Manager. • If no data is received, check the subnetwork cables. Also verify that the transmitted data is correct.

D. ASCII Table

	x0	x1	x2	x3	x4	x5	x6	x7	x8	x9	xA	xB	xC	xD	xE	xF
0x	NUL 0	SOH 1	STX 2	ETX 3	EOT 4	ENQ 5	ACK 6	BEL 7	BS 8	HT 9	LF 10	VT 11	FF 12	CR 13	SO 14	SI 15
1x	DLE 16	DC1 17	DC2 18	DC3 19	DC4 20	NAK 21	SYN 22	ETB 23	CAN 24	EM 25	SUB 26	ESC 27	FS 28	GS 29	RS 30	US 31
2x	(sp) 32	! 33	" 34	# 35	$ 36	% 37	& 38	' 39	(40	) 41	* 42	+ 43	, 44	- 45	. 46	/ 47
3x	0 48	1 49	2 50	3 51	4 52	5 53	6 54	7 55	8 56	9 57	: 58	; 59	< 60	= 61	> 62	? 63
4x	@ 64	A 65	B 66	C 67	D 68	E 69	F 70	G 71	H 72	I 73	J 74	K 75	L 76	M 77	N 78	O 79
5x	P 80	Q 81	R 82	S 83	T 84	U 85	V 86	W 87	X 88	Y 89	Z 90	[91	\ 92	] 93	^ 94	_ 95
6x	` 96	a 97	b 98	c 99	d 100	e 101	f 102	g 103	h 104	i 105	j 106	k 107	l 108	m 109	n 110	o 111
7x	p 112	q 113	r 114	s 115	t 116	u 117	v 118	w 119	x 120	y 121	z 122	{ 123	| 124	} 125	~ 126	DEL 127